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APPLICATION OF SENSITIVITY ANALYSIS IN EXPERIMENTS DESIGN

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Abstract. The system casting-mould is considered and it is assumed that the aim of experiments is to determine the course of substitute thermal capacity of casting material. The casting is made from cast iron and the austenite and eutectic latent heats should be identified. To find the optimal location of sensors the methods of sensitivity analysis are applied. In the final part of the paper the results of computations are shown.

1. Governing equations

The energy equation describing the casting solidification has the following form [1, 2]

$$x \in \Omega: \quad C(T) \frac{\partial T(x, t)}{\partial t} = \nabla \left[\lambda(T) \nabla T(x, t) \right]$$
(1)

where C(T) is the substitute thermal capacity of cast iron, λ is the thermal conductivity, T, x, t denote the temperature, geometrical co-ordinates and time.

The equation considered is supplemented by the equation concerning a mould sub-domain

$$x \in \Omega_m: \ c_m \frac{\partial T_m(x,t)}{\partial t} = \lambda_m \nabla^2 T_m(x,t)$$
(2)

where c_m is the mould volumetric specific heat, λ_m is the mould thermal conductivity.

In the case of typical sand moulds on the contact surface between casting and mould the continuity condition in the form

$$x \in \Gamma_c: \begin{cases} -\lambda(T)\mathbf{n} \cdot \nabla T(x, t) = -\lambda_m \mathbf{n} \cdot \nabla T_m(x, t) \\ T(x, t) = T_m(x, t) \end{cases}$$
(3)

can be accepted.

On the external surface of the system the Robin condition

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$$x \in \Gamma_0: -\lambda_m \mathbf{n} \cdot \nabla T_m(x, t) = \alpha \Big[T_m(x, t) - T_a \Big]$$
(4)

is given (α is the heat transfer coefficient, T_a is the ambient temperature). For time t = 0 the initial condition

$$t = 0: \quad T(x, 0) = T_0(x) \quad , \quad T_m(x, 0) = T_{m0}(x) \tag{5}$$

is also known.

In the case of cast iron solidification the following approximation of substitute thermal capacity can be taken into account (Fig. 1)

$$C(T) = \begin{cases} c_{L}, & T > T_{L} \\ c_{P} + \frac{Q_{aus1}}{T_{L} - T_{A}}, & T_{A} < T \le T_{L} \\ c_{P} + \frac{Q_{aus2}}{T_{A} - T_{E}}, & T_{E} < T \le T_{A} \\ c_{P} + \frac{Q_{eu}}{T_{E} - T_{S}}, & T_{S} < T \le T_{E} \\ c_{S}, & T \le T_{S} \end{cases}$$
(6)

where T_L , T_A , T_E , T_S correspond to the border temperatures, c_L , c_S , $c_P = 0.5 \cdot (c_L + c_S)$ are the constant volumetric specific heats of molten metal, solid state and mushy zone sub-domain, $Q_{aus} = Q_{aus1} + Q_{aus2}$, Q_{eu} are the latent heats connected with the austenite and eutectic phases evolution, at the same time $Q = Q_{aus} + Q_{eu}$.

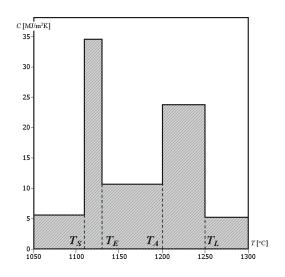


Fig. 1. Substitute thermal capacity of cast iron

The thermal conductivity is defined as follows

$$\lambda(T) = \begin{cases} \lambda_L, & T > T_L \\ \lambda_P, & T_S \le T \le T_L \\ \lambda_S, & T < T_S \end{cases}$$
(7)

where λ_L , λ_S , $\lambda_P = 0.5 \cdot (\lambda_L + \lambda_S)$ are the constant thermal conductivities of liquid state, solid state and mushy zone sub-domain, respectively.

2. Sensitivity analysis

It is assumed that the aim of experiments is to determine the latent heats Q_{aus1} , Q_{aus2} , Q_{eu} of casting material (an inverse problem) and in order to find the optimal location of sensors the sensitivity analysis methods [3-5] are applied.

To determine the sensitivity functions the governing equations (1)-(5) are differentiated with respect to $p_1 = Q_{aus1}$, $p_2 = Q_{aus2}$ and $p_3 = Q_{eu}$. So, the following additional problems should be solved

$$\begin{aligned} x \in \Omega : \frac{\partial C(T)}{\partial p_{e}} \frac{\partial T(x,t)}{\partial t} + C(T) \frac{\partial}{\partial p_{e}} \left(\frac{\partial T(x,t)}{\partial t} \right) &= \\ & \frac{\partial}{\partial p_{e}} \left[\nabla \left[\lambda(T) \nabla T(x,t) \right] \right] \\ x \in \Omega_{m} : c_{m} \frac{\partial}{\partial p_{e}} \left(\frac{\partial T_{m}(x,t)}{\partial t} \right) &= \lambda_{m} \frac{\partial}{\partial p_{e}} \left[\nabla^{2} T_{m}(x,t) \right] \\ x \in \Gamma_{e} : \begin{cases} -\frac{\partial}{\partial p_{e}} \left[\lambda(T) \mathbf{n} \cdot \nabla T(x,t) \right] &= -\lambda_{m} \mathbf{n} \cdot \frac{\partial}{\partial p_{e}} \left[\nabla T_{m}(x,t) \right] \\ & \frac{\partial T(x,t)}{\partial p_{e}} &= \frac{\partial T_{m}(x,t)}{\partial p_{e}} \end{cases} \end{aligned}$$
(8)
$$x \in \Gamma_{0} : -\lambda_{m} \mathbf{n} \cdot \frac{\partial}{\partial p_{e}} \left[\nabla T_{m}(x,t) \right] &= 0 \\ t = 0 : \quad \frac{\partial T(x,0)}{\partial p_{e}} &= 0 , \quad \frac{\partial T_{m}(x,0)}{\partial p_{e}} &= 0 \end{aligned}$$

or

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$$x \in \Omega: C(T) \frac{\partial Z_{e}(x,t)}{\partial t} = \nabla [\lambda(T) \nabla Z_{e}(x,t)] + \nabla \left[\frac{\partial \lambda(T)}{\partial p_{e}} \nabla T(x,t)\right] - \frac{\partial C(T)}{\partial p_{e}} \frac{\partial T(x,t)}{\partial t}$$

$$x \in \Omega_{m}: c_{m} \frac{\partial Z_{me}(x,t)}{\partial t} = \lambda_{m} \nabla^{2} Z_{me}(x,t) \qquad (9)$$

$$x \in \Gamma_{c}: \begin{cases} -\frac{\partial \lambda(T)}{\partial p_{e}} \mathbf{n} \cdot \nabla T(x,t) - \lambda(T) \mathbf{n} \cdot \nabla Z_{e}(x,t) = -\lambda_{m} \mathbf{n} \cdot \nabla Z_{me}(x,t) \\ Z_{e}(x,t) = Z_{me}(x,t) \end{cases}$$

$$x \in \Gamma_{0}: -\lambda_{m} \mathbf{n} \cdot \nabla Z_{me}(x,t) = 0$$

$$t = 0: \quad Z_{e}(x,0) = 0 \quad , \quad Z_{me}(x,0) = 0$$

where

$$Z_{e}(x,t) = \frac{\partial T(x,t)}{\partial p_{e}}, \quad Z_{me}(x,t) = \frac{\partial T_{m}(x,t)}{\partial p_{e}}$$
(10)

Differentiation of substitute thermal capacity with respect to the parameters p_1 , p_2 , p_3 leads to the following formulas

$$\frac{\partial C(T)}{\partial p_{1}} = \begin{cases}
0, & T > T_{L} \\
1/(T_{L} - T_{A}), & T_{A} < T \le T_{L} \\
0, & T_{E} < T \le T_{A} \\
0, & T_{S} < T \le T_{E} \\
0, & T \le T_{S}
\end{cases}$$
(11)
$$\frac{\partial C(T)}{\partial p_{2}} = \begin{cases}
0, & T > T_{L} \\
0, & T_{A} < T \le T_{L} \\
1/(T_{A} - T_{E}), & T_{E} < T \le T_{A} \\
0, & T_{S} < T \le T_{E} \\
0, & T \le T_{S}
\end{cases}$$
(12)

and

$$\frac{\partial C(T)}{\partial p_{3}} = \begin{cases} 0, & T > T_{L} \\ 0, & T_{A} < T \le T_{L} \\ 0, & T_{E} < T \le T_{L} \\ 0, & T_{E} < T \le T_{L} \\ 0, & T_{E} < T \le T_{L} \\ 0, & T \le T_{S} \end{cases}$$
(13)

3. Example of computations

The casting-mould system shown in Figure 2 has been considered. The basic problem and additional problems connected with the sensitivity functions have been solved using the explicit scheme of FDM [1]. The regular mesh created by 25×15 nodes with constant step h = 0.002 m has been introduced, time step $\Delta t = 0.1$ s. The following input data have been assumed: $\lambda_L = 20$ W/(mK), $\lambda_S = 40$ W/(mK), $\lambda_m = 1$ W/(mK), $c_L = 5.88$ MJ/(m³ K), $c_S = 5.4$ MJ/(m³ K), $Q_{aus1} = 937.2$ MJ/m³, $Q_{aus2} = 397.6$ MJ/m³, $Q_{eu} = 582.2$ MJ/m³, $c_m = 1.75$ MJ/(m³ K), pouring temperature $T_0 = 1300^{\circ}$ C, liquidus temperature $T_L = 1250^{\circ}$ C, border temperatures $T_A = 1200^{\circ}$ C, $T_E = 1130^{\circ}$ C, solidus temperature $T_S = 1110^{\circ}$ C, initial mould temperature $T_{m0} = 20^{\circ}$ C.

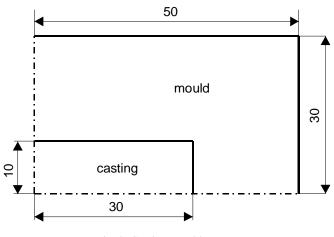


Fig. 2. Casting-mould system

In Figures 3-5 the distributions of functions $Z_1 \cdot 10^9$, $Z_2 \cdot 10^9$, $Z_3 \cdot 10^9$ in the domain of casting for different times are shown. It is visible, that maximal values of sensitivity functions for different times appear in different places, but the global maximum corresponds to the point 1 (0, 0) marked in Figure 8. Figures 6 and 7 illustrate the courses of sensitivity functions at the points 1 and 2 shown in Figure 8.

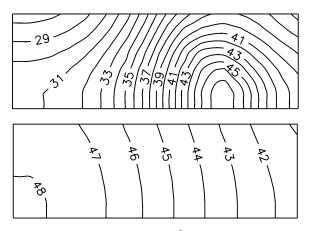


Fig. 3. Distribution of function $Z_1 \cdot 10^9$ for times 30 and 90 second

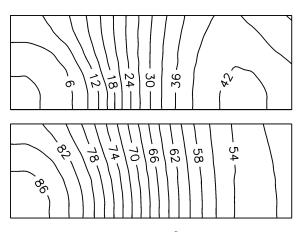


Fig. 4. Distribution of function $Z_2 \cdot 10^9$ for time 60 and 120 second

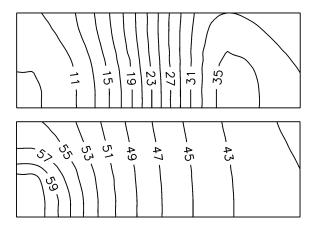


Fig. 5. Distribution of function $Z_3 \cdot 10^9$ for time 120 and 180 second

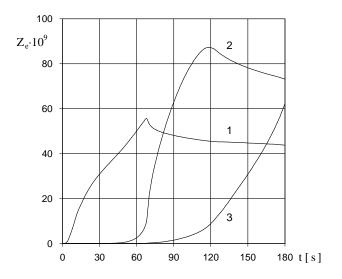


Fig. 6. Courses of sensitivity functions at the point 1 (0, 0)

On the basis of sensitivity functions analysis the optimal location of sensors can be determined (see. Fig. 8).

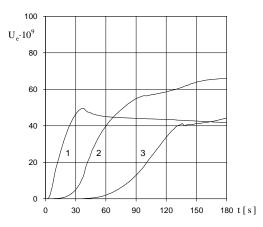


Fig. 7. Courses of sensitivity functions at the point 2 (0.02, 0)

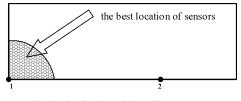


Fig. 8. Optimal position of sensors

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