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THE POLYNOMIAL TENSOR INTERPOLATION

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Abstract. In this paper the tensor interpolation by polynomials of several variables is considered.

Introduction

The formulas of tensor interpolation by polynomials of several variables are the unknow in the interpolation methods ([1]). Using the Kronecker tensor product of matrices ([2, 3]) the polynomial tensor interpolation formula was given in tis article.

1. The Kronecker product of matrices

The Kronecker product of two matrices $A = \begin{bmatrix} a_{ij} \end{bmatrix}$ and $B = \begin{bmatrix} b_{ij} \end{bmatrix}$ of degrees respectively *m* and *n* we define as a matrix given in block form as:

$$A \otimes B = [a_{ij}B] = \begin{bmatrix} a_{11}B & a_{12}B & \dots & a_{1m}B \\ a_{21}B & a_{22}B & \dots & a_{2m}B \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1}B & a_{m2}B & \dots & a_{mm}B \end{bmatrix}$$

we denote the Kronecker product of A and B by $A \otimes B$. The Kronecker product is also known as the *direct product* or the *tensor product*.

Some properties for Kronecker products of two matrices:

- 1. The matrices $A \otimes B$ and $B \otimes A$ are orthogonaly similar, which means that square matrix U exists and $B \otimes A = U^{t}(A \otimes B)U$, $U^{t}U = I$.
- 2. If A,B,C,D are square matrices such that the products AC and BD exist, then $(A \otimes B)(C \otimes D)$ exist and

$$(A \otimes B)(C \otimes D) = AC \otimes BD$$

(the "Mixed Product Rule")

- 3. $(\alpha A) \otimes (\beta B) = \alpha \beta (A \otimes B)$
- 4. $(A \otimes B)^t = A^t \otimes B^t$
- 5. If A and B are invertible matrices, then $(A \otimes B)^{-1} = A^{-1} \otimes B^{-1}$
- 6. $\det(A \otimes B) = (\det A)^n (\det B)^m$
- 7. the $(a \otimes b)_{rs}$ element of the matrix $A \otimes B$ is given by the product

$$(a \otimes b)_{rs} = a_{ij}b_{kl}$$

where r = (i-1)n + k, s = (j-1)n + l.

Next, we consider the quadratic matrices $A_1 = [(a_1)_{i_1 j_1}], ..., A_k = [(a_k)_{i_k j_k}]$ of degrees respectively $n_1, ..., n_k$ and define the tensor product inductively:

$$A_1 \otimes A_2 \otimes \ldots \otimes A_k = (A_1 \otimes A_2 \otimes \ldots \otimes A_{k-1}) \otimes A_k$$

for $k \ge 3$.

Some properties for Kronecker products:

- 1. The matrices $A_{\sigma(1)} \otimes A_{\sigma(2)} \otimes ... \otimes A_{\sigma(k)}$ and $A_1 \otimes A_2 \otimes ... \otimes A_k$, where σ is any determine permutation of numbers 1,..., k, are orthogonaly similar. It means that square matrix U_{σ} exists and $A_{\sigma(1)} \otimes A_{\sigma(2)} \otimes ... \otimes A_{\sigma(k)} =$ $= U_{\sigma}^{t} (A_1 \otimes A_2 \otimes ... \otimes A_k) U_{\sigma}, \quad U_{\sigma}^{t} U_{\sigma} = I.$
- 2. $(A_1 \otimes A_2 \otimes ... \otimes A_k)(B_1 \otimes B_2 \otimes ... \otimes B_k) = (A_1B_1) \otimes (A_2B_2) \otimes ... \otimes (A_kB_k)$ provided the dimensions of the matrices are such that the various expressions exist (the "Mixed Product Rule").
- 3. $(\alpha_1 A_1) \otimes (\alpha_2 A_2) \otimes ... \otimes (\alpha_k A_k) = \alpha_1 \alpha_2 ... \alpha_k (A_1 \otimes A_2 \otimes ... \otimes A_k)$
- 4. $(A_1 \otimes A_2 \otimes ... \otimes A_k)^t = A_1^t \otimes A_2^t \otimes ... \otimes A_k^t$
- 5. if A_1, \dots, A_k are invertible matrices, then: $(A_1 \otimes A_2 \otimes \dots \otimes A_k)^{-1} = A_1^{-1} \otimes A_2^{-1} \otimes \dots \otimes A_k^{-1}$
- 6. $\det(A_1 \otimes A_2 \otimes \ldots \otimes A_k) = (\det A_1)^{\hat{n}_1 n_2 \dots n_k} (\det A_2)^{n_1 \hat{n}_2 \dots n_k} \dots (\det A_k)^{n_1 n_2 \dots \hat{n}_k}$ where \hat{n}_i is omission.
- 7. the $(a_1 \otimes a_2 \otimes ... \otimes a_k)_{ij}$ element of the matrix $A_1 \otimes A_2 \otimes ... \otimes A_k$ is given by the product $(a_1 \otimes a_2 \otimes ... \otimes a_k)_{ij} = (a_1)_{i_1 j_1} (a_2)_{i_2 j_2} ... (a_k)_{i_k j_k}$, where: $i = (i_1 - 1)\hat{n}_1 n_2 ... n_k + (i_2 - 1)\hat{n}_1 \hat{n}_2 ... n_k + ... + (i_{k-1} - 1)n_k + i_k$

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2. One of the property for Vandermonde's matrix

Consider the Vandermonde's matrix:

$$V_{p+1} = V_{p+1} \Big(X_0, X_1, X_2, \dots, X_p \Big) = \begin{bmatrix} 1 & X_0 & \dots & X_0^p \\ 1 & X_1 & \dots & X_1^p \\ \vdots & \vdots & \ddots & \vdots \\ 1 & X_p & \dots & X_p^p \end{bmatrix}$$

of degree p+1.

The algebraic complement of the matrix V_{p+1} , has the form

$$D_{ij} = (-1)^{i+j} \tau_{p-j} (X_0, ..., \hat{X}_i, ..., X_p) \det V_p (X_0, ..., \hat{X}_i, ..., X_p)$$

where $\tau_{p-j}(X_0,...,\hat{X}_i,...,X_p)$ design the fundamental symmetric τ_{p-j} polynomial of the rank p-j of variables $X_0,...,\hat{X}_i,...,X_p$, and the symbol \hat{X}_i means omitting the variable X_i ($\tau_0 = 0$). Similarly for Vandermonde's determinant $det V_p$. This property we easly obtain on the one hand by evolving determinant

$$\det V_{p+1} = \det \begin{bmatrix} 1 & X_0 & \dots & X_0^p \\ 1 & X_1 & \dots & X_1^p \\ \vdots & \vdots & \ddots & \vdots \\ 1 & X_p & \dots & X_p^p \end{bmatrix} = \prod_{0 \le k < l \le p} (X_l - X_k)$$

according to *i*-th row, and on the other hand by sorting its value according to X_i variable power. In particular

$$\frac{D_{ij}}{\det V_{p+1}} = \frac{(-1)^{i+j} \tau_{p-j} (X_0, ..., \hat{X}_i, ..., X_p)}{\Pi_i}$$

where

$$\Pi_{i} = \prod_{\substack{0 \le k < l < p \\ k \ne i \text{ or } l \ne i}} (X_{l} - X_{k}) = (X_{p} - X_{i})..(X_{i+1} - X_{i})(X_{i} - X_{i-1})..(X_{i} - X_{0})$$

3. The polynomial tensor interpolation

The coefficients matrix $[a_{j_1...j_k}]$ of the polynomial interpolation

$$W(X_1,...,X_k) = \sum_{0 \le j_1 \le p_1,...,0 \le j_k \le p_k} a_{j_1...j_k} X_1^{j_1} \dots X_k^{j_k}$$

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are unknow. The results matrix $[(w_1)_{i_1}...(w_k)_{i_k}] = [w_{i_1...i_k}]$ and the nodes matrix $[(X_1)_{i_1} \times ... \times (X_k)_{i_k}] = [X_{1i_1}...X_{ki_k}]$ are know. The coefficients of the polynomial are determined from the linear system

$$\left(\left[X_{i_{1}}^{j_{1}}\right]\otimes\ldots\otimes\left[X_{i_{k}}^{j_{k}}\right]\right)\operatorname{vec}\left[a_{j_{1}\ldots j_{k}}\right]=\operatorname{vec}\left[w_{i_{1}\ldots i_{k}}\right]$$

where the nodes matrix is the Kronecker product of Vandermonde's matrices $V_{p_1+1} = \begin{bmatrix} X_{1i_1}^{j_1} \end{bmatrix}, ..., V_{p_k+1} = \begin{bmatrix} X_{ki_k}^{j_k} \end{bmatrix}$, and the operator "vec" put coefficient matrix $\begin{bmatrix} a_{j_1...j_k} \end{bmatrix}$ and results matrix $\begin{bmatrix} w_{i_1...i_k} \end{bmatrix}$ in columns, attributing multiindexes $j_1...j_k$ and $i_1...i_k$ properly positions

$$j = j_1(\hat{p}_1 + 1)(p_2 + 1)...(p_k + 1) + j_2(\hat{p}_1 + 1)(\hat{p}_2 + 1)...(p_k + 1) + ... + j_{k-1}(p_k + 1) + j_k + 1$$

and

$$i = i_1 (\hat{p}_1 + 1) (p_2 + 1) \dots (p_k + 1) + i_2 (\hat{p}_1 + 1) (\hat{p}_2 + 1) \dots (p_k + 1) + \dots + i_{k-1} (p_k + 1) + i_k + 1$$

of the $a_{j_1...j_k}$ element in coefficients column and $w_{i_1...i_k}$ element in results column. It means that we select ordering

$$00...00, 00...01, ..., 00...0p_k, 0...1p_k, ..., 00...p_{k-1}p_k, ..., 0p_2...p_{k-1}p_k, ..., p_1...p_{k-1}p_k$$

with sequence shown above.

Then the searching coefficients column has a form

$$vec[a_{j_{1}...j_{k}}] = \frac{1}{\det[X_{1i_{1}}^{j_{1}}]} \cdots \frac{1}{\det[X_{ki_{k}}^{j_{k}}]} (D_{V_{1}} \otimes ... \otimes D_{V_{k}})^{t} vec[w_{i_{1}...i_{k}}]$$

where: $V_1 = V_{p_1+1} = \left[X_{li_1}^{j_1}\right], ..., V_k = V_{p_k+1} = \left[X_{ki_k}^{j_k}\right].$ According to property 7' we obtain the formula for coefficients

$$a_{j_1...j_k} = \sum_{0 \le i_1 \le p_1,...,0 \le i_k \le p_k} w_{i_1...i_k} \frac{\left(D_{V_1}\right)_{i_1 j_1}}{\det V_1} \cdots \frac{\left(D_{V_k}\right)_{i_k j_k}}{\det V_k}$$

and because fractions shown above has got known form then:

$$a_{j_{1}...j_{k}} = \sum_{0 \le i_{1} \le p_{1},...,0 \le i_{k} \le p_{k}} (-1)^{I^{+}+J^{+}} w_{i_{1}...i_{k}} \frac{\tau_{p_{1}-j_{1}} \left(X_{10},...,\hat{X}_{1i_{1}},...,X_{1p_{1}}\right)}{\Pi_{1i_{1}}}$$
$$\dots \frac{\tau_{p_{k}-j_{k}} \left(X_{k0},...,\hat{X}_{ki_{k}},...,X_{kp_{k}}\right)}{\Pi_{ki_{k}}}$$

where: $I^+ = i_1 + \ldots + i_k$, $J^+ = j_1 + \ldots + j_k$ and

$$\Pi_{1i_1} = (X_{1p_1} - X_{1i_1}) .. (X_{1i_1+1} - X_{1i_1}) (X_{1i_1} - X_{1i_1-1}) .. (X_{1i_1} - X_{10})$$

$$\Pi_{ki_{k}} = (X_{kp_{k}} - X_{ki_{k}}) .. (X_{ki_{k}+1} - X_{ki_{k}}) (X_{ki_{k}} - X_{ki_{k}-1}) .. (X_{ki_{k}} - X_{k0})$$

And now the polynomial coefficient we can obtain numerically.

References

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