

THERMO-DIFFUSION MHD CONVECTION IN ENCLOSURE USING HEAT AND MASS LINES VISUALIZATION TECHNIQUES

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Abstract. The numerical study of two-dimensional laminar thermo-diffusion natural convection in an exponentially heated and concentrated square enclosure of unit length in the presence of a uniform horizontal magnetic field is presented in this paper. The left and right vertical walls are assumed to have higher and lower temperatures and concentrations, respectively, and are governed by exponential functions, whereas the horizontal walls are assumed to be adiabatic and non-diffusive. The mathematical formulation of heat and mass functions has been completed, and heat and mass line contours have been drawn based on these functions to investigate the behavior of heat and mass in the cavity. The flow governing equations were solved using a finite difference method in conjunction with the Successive Over-Relaxation (SOR) technique and then converted to a vorticity-stream function form. A detailed comparison of isotherms with heatlines and isosolutes with masslines has been performed. Furthermore, the reduction for lower Rayleigh numbers Ra surpassing the reduction for higher values of Ra . The maximum reduction in overall heat and mass transfer has been observed for higher Hartmann ($Ha = 8$).

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Nomenclature

English letters	(x, y)	dimensional coordinates [m]	
β_{S^*}	solute expansion coefficient	Nu	Nusselt number
β_{T^*}	thermal expansion coefficient	Sh	Sherwood number
(U, V)	dimensionless velocity components	g	gravitational acceleration [$m s^{-2}$]
(u, v)	dimensional velocity components [ms^{-1}]	B	magnetic field strength
(X, Y)	dimensionless coordinates	D	mass diffusivity [$m^2 s^{-1}$]
		H	dimensionless heat function

h	dimensional heat function	μ	dynamic viscosity $[\text{Kgm}^{-1}\text{s}^{-1}]$
J	heat flux	ν	kinematic viscosity $[\text{m}^2\text{s}^{-1}]$
L	enclosure side	Ω	dimensionless vorticity
M	dimensionless mass function	ω	dimensional vorticity
m	dimensional mass function	ρ	fluid density $[\text{Kgm}^{-3}]$
N	buoyancy ratio	σ	electrical conductivity $[\text{Wm}^{-1}\text{K}^{-1}]$
P	dimensionless pressure	k	thermal conductivity $[\text{Wm}^{-1}\text{K}^{-1}]$
p	dimensional pressure $[\text{Nm}^{-2}]$	Subscripts	
S	dimensionless solute	avg	average
S^*	dimensional solute $[\text{Kgm}^{-3}]$	min	maximum
T	dimensionless temperature	min	minimum
T^*	dimensional temperature $[\text{K}]$	h	higher
Greek symbols		l	lower
α	thermal diffusivity $[\text{m}^2\text{s}^{-1}]$		

1. Introduction

The process of thermo-diffusion natural convection is governed by the combined temperature and concentration gradients. The most recent works [1–4] show that isotherms, isoconcentration, and streamlines are frequently used to investigate the thermo-diffusion natural convection phenomenon. The streamlines visualization technique effectively depicts fluid flow. The isotherms and isoconcentrations are used to visualize the heat and mass flows within the domain, but they cannot represent the ‘heat flow’ and ‘mass flow’ because the isotherms and isoconcentrations only indicate the spatial distribution of temperature and concentration. Understanding the heat and mass flow during thermo-diffusion convection requires a visualization tool similar to streamlines. As a result, we use the heat and mass lines techniques to fully visualize ‘heat flow’ and ‘mass flow,’ respectively. Only a few authors have used heat and mass lines techniques to fully visualize heat and mass flows in cavities. We’ve listed a few of them here where the authors used the aforementioned visualization techniques. The visualization tools for heat and mass lines were used in [5–7]. Some very important contributions have been done by Prof. Sohail A. Khan and his group members in the numerical investigation of heat transfer with entropy generation minimization [8–11] in various types of nanofluids in numerous types of geometries. Furthermore, they have also investigated double-diffusion in Sisko fluid flow with variable properties [12], heat transfer and entropy analysis using liquid hydrogen based nanoliquid [13] and mixed convection utilizing CNTs [14,15] as well as Ree-Eyring nanofluid flow with entropy generation analysis [16].

2. Problem formulation

The current study's problem formulation is divided into two parts: the physical model is explained in the first part, and the mathematical formulation is presented in the second part.

2.1. Physical model

The current work considers steady, laminar, and incompressible flow in a square enclosure, as shown in Figure 1. Water, a Newtonian fluid, has been considered as the working fluid ($Pr = 6.2$). The left wall is kept at a higher temperature and solute concentration, while the right wall is kept at a lower temperature and solute concentration. Along the horizontal walls, heat and mass transmissions are adiabatic. No-slip velocity boundary conditions, i.e., $u = v = 0$, apply to all solid walls. A uniform magnetic field of strength B is applied in the x -direction.

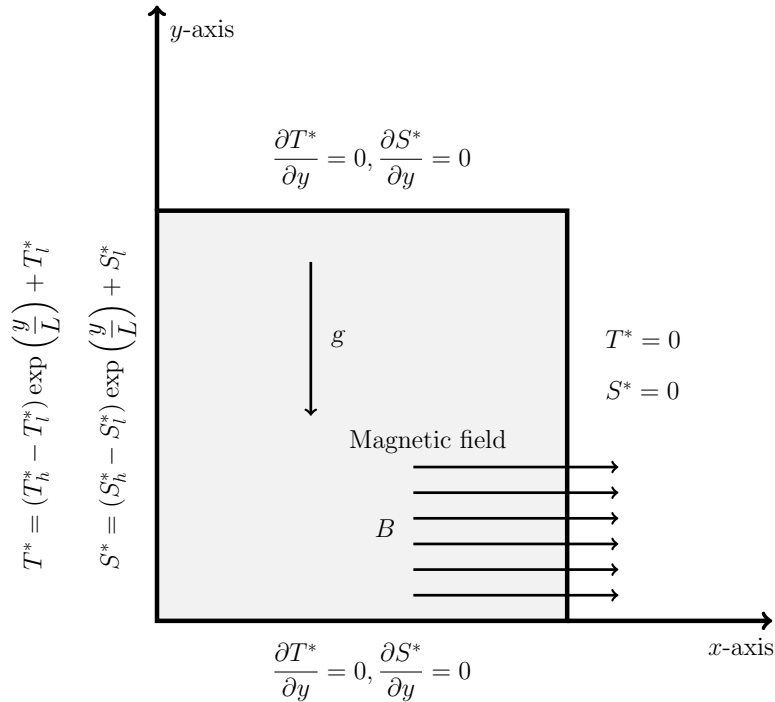


Fig. 1. The physical model of the problem under consideration

2.2. Mathematical formulation

The current study's mathematical formulation was derived from a physical model that included flow controlling equations in dimensional and non-dimensional forms,

as well as boundary conditions. In addition, the dimensional and non-dimensional forms of steam, heat, and mass functions are addressed. The flow governing equations which are continuity, momentum, energy, and solute transfer equations in dimensional form are as follows [7]:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0, \quad (1)$$

$$\rho \left(u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} \right) = -\frac{\partial p}{\partial x} + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right), \quad (2)$$

$$\rho \left(u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} \right) = -\frac{\partial p}{\partial y} + \mu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) + (\rho \beta_{T^*}) g (T^* - T_l^*) + (\rho \beta_{S^*}) g (S^* - S_l^*) - \sigma B^2 v, \quad (3)$$

$$(\rho c_p) \left(u \frac{\partial T^*}{\partial x} + v \frac{\partial T^*}{\partial y} \right) = k \left(\frac{\partial^2 T^*}{\partial x^2} + \frac{\partial^2 T^*}{\partial y^2} \right), \quad (4)$$

$$u \frac{\partial S^*}{\partial x} + v \frac{\partial S^*}{\partial y} = D \left(\frac{\partial^2 S^*}{\partial x^2} + \frac{\partial^2 S^*}{\partial y^2} \right). \quad (5)$$

Using stream function $\left(u = \frac{\partial \Psi}{\partial y}, v = -\frac{\partial \Psi}{\partial x} \right)$, vorticity $\left(\omega = \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right)$ transformation along with the following non-dimensional parameters

$$\begin{aligned} X &= \frac{x}{L}, \quad Y = \frac{y}{L}, \quad U = \frac{uL}{\alpha_f}, \quad V = \frac{vL}{\alpha}, \quad \Psi = \frac{\Psi}{\alpha}, \quad P = \frac{\rho L^2}{\rho \alpha^2} \\ \text{Pr} &= \frac{\nu}{\alpha}, \quad \text{Le} = \frac{\alpha}{D}, \quad \Omega = \frac{\omega L^2}{\alpha}, \quad T = \frac{T^* - T_l^*}{T_h^* - T_l^*}, \quad S = \frac{S^* - S_l^*}{S_h^* - S_l^*} \\ \text{Ra} &= \frac{g \beta_{T^*} (T_h^* - T_l^*) L^3}{\nu \alpha}, \quad \text{N} = \frac{(\rho \beta_{S^*}) (S_h^* - S_l^*)}{(\rho \beta_{T^*}) (T_h^* - T_l^*)}, \quad \text{Ha} = BL \sqrt{\frac{\sigma}{\mu}}, \end{aligned} \quad (6)$$

the non-dimensional form of Eqs. (1) to (5) in stream function, vorticity, temperature, and solute equations are as follows:

$$\frac{\partial^2 \Psi}{\partial X^2} + \frac{\partial^2 \Psi}{\partial Y^2} = -\Omega \quad (7)$$

$$U \frac{\partial \Omega}{\partial X} + V \frac{\partial \Omega}{\partial Y} = \text{Pr} \left(\frac{\partial^2 \Omega}{\partial X^2} + \frac{\partial^2 \Omega}{\partial Y^2} \right) + \text{RaPr} \left(\frac{\partial T}{\partial X} + \text{N} \frac{\partial S}{\partial X} \right) - \text{Ha}^2 \text{Pr} \frac{\partial V}{\partial X}, \quad (8)$$

$$U \frac{\partial T}{\partial X} + V \frac{\partial T}{\partial Y} = \frac{\partial^2 T}{\partial X^2} + \frac{\partial^2 T}{\partial Y^2}, \quad (9)$$

$$U \frac{\partial S}{\partial X} + V \frac{\partial S}{\partial Y} = \frac{1}{Le} \left(\frac{\partial^2 S}{\partial X^2} + \frac{\partial^2 S}{\partial Y^2} \right), \quad (10)$$

The following are the non-dimensional boundary conditions for the non-dimensional flow governing Eqs. (7) to (10) [17, 18]:

$$\begin{aligned} \Psi = 0, \Omega = -\frac{\partial^2 \Psi}{\partial Y^2}, \quad \frac{\partial T}{\partial Y} = \frac{\partial S}{\partial Y} = 0, \text{ along horizontal walls,} \\ \Psi = 0, \Omega = -\frac{\partial^2 \Psi}{\partial X^2}, \quad T = S = 0, \text{ along the right wall,} \\ \Psi = 0, \Omega = -\frac{\partial^2 \Psi}{\partial X^2}, \quad T = S = \exp(Y), \text{ along the left wall.} \end{aligned} \quad (11)$$

2.2.1. Stream function (Streamlines)

The non-dimensional stream function (Ψ) that governs the flow structure is defined as follows:

$$U = \frac{\partial \Psi}{\partial Y} \quad \text{and} \quad V = -\frac{\partial \Psi}{\partial X} \quad (12)$$

After manipulation, Eq. (12) can be rewritten as follows:

$$\frac{\partial^2 \Psi}{\partial X^2} + \frac{\partial^2 \Psi}{\partial Y^2} = \frac{\partial U}{\partial Y} - \frac{\partial V}{\partial X}. \quad (13)$$

Equation (13) is Poisson's equation for the non-dimensional stream function Ψ with source term $\frac{\partial U}{\partial Y} - \frac{\partial V}{\partial X}$. The solution to Eq. (13) yields the non-dimensional stream function, $\Psi(X, Y)$, and sketching isolines of this yields streamlines inside the enclosure.

2.2.2. Heat function (Heatlines)

The total heat flux vector, $\vec{J} = (J_x \vec{i} + J_y \vec{j})$, containing the diffusion and convection transport, in x and y directions can be written as

$$J_x = (\rho c_p) u (T^* - T_l^*) - k \frac{\partial T^*}{\partial x}, \quad J_y = (\rho c_p) v (T^* - T_l^*) - k \frac{\partial T^*}{\partial y} \quad (14)$$

$$\frac{\partial J_x}{\partial x} + \frac{\partial J_y}{\partial y} = (\rho c_p) \left(\frac{\partial u T^*}{\partial x} + \frac{\partial v T^*}{\partial y} \right) - k \left(\frac{\partial^2 T^*}{\partial x^2} + \frac{\partial^2 T^*}{\partial y^2} \right) = 0 \quad (15)$$

The dimensional heat function can be expressed in a differential form by treating h as a continuous scalar function [19, 20]:

$$-\frac{\partial h}{\partial x} = J_y, \quad \frac{\partial h}{\partial y} = J_x \quad (16)$$

Therefore, from Eq. (14) we have

$$-\frac{\partial h}{\partial x} = (\rho c_p) v (T^* - T_l^*) - k \frac{\partial T^*}{\partial y} \quad (17)$$

$$\frac{\partial h}{\partial y} = (\rho c_p) u (T^* - T_l^*) - k \frac{\partial T^*}{\partial x} \quad (18)$$

Using the non-dimensional parameters described in Eq. (6), we may express Eqs. (17) and (18) in the dimensionless form as follows:

$$-\frac{\partial H}{\partial X} = VT - \frac{\partial T}{\partial Y} \quad (19)$$

$$\frac{\partial H}{\partial Y} = UT - \frac{\partial T}{\partial X} \quad (20)$$

where H stands for the dimensionless heat function and is written as

$$H = \frac{h}{k(T_h^* - T_l^*)} \quad (21)$$

The manipulation of Eqs. (19) and (20) yields the following partial differential equation for the heat function.

$$\frac{\partial^2 H}{\partial X^2} + \frac{\partial^2 H}{\partial Y^2} = \frac{\partial(UT)}{\partial Y} - \frac{\partial(VT)}{\partial X} \quad (22)$$

By solving either Eq. (19), Eq. (20), or Eq. (22), we can obtain the dimensionless heat function H in the inner region of the rectangular enclosure under consideration. Heatlines are created by creating isolines with the heat function.

The following are the corresponding boundary conditions for the heat function H :

$$\begin{aligned} \text{for, } X = 0 \quad \text{and} \quad X = 1, \quad \frac{\partial H}{\partial X} &= 0, \\ \text{for, } Y = 0, \quad H &= 0, \\ \text{for, } Y = 1, \quad H &= \text{Nu}_{\text{avg}}, \end{aligned} \quad (23)$$

where Nu_{avg} is given by

$$Nu_{\text{avg}} = \int_0^1 Nu \, dY \quad (24)$$

and

$$Nu = - \left. \frac{\partial T}{\partial X} \right|_{X=0}. \quad (25)$$

2.2.3. Mass function (Masslines)

In the dimensional form, the mass function [20, 21] is given as m and defined as

$$- \frac{\partial m}{\partial x} = \rho v (S^* - S_l^*) - \rho D \frac{\partial S^*}{\partial y} \quad (26)$$

$$\frac{\partial m}{\partial y} = \rho u (S^* - S_l^*) - \rho D \frac{\partial S^*}{\partial x} \quad (27)$$

Using the non-dimensional parameters described in Eq. (6), we may express Eqs. (26) and (27) in the dimensionless form as follows:

$$- \frac{\partial M}{\partial X} = VS - \frac{1}{Le} \frac{\partial S}{\partial Y} \quad (28)$$

$$\frac{\partial M}{\partial Y} = US - \frac{1}{Le} \frac{\partial S}{\partial X} \quad (29)$$

where M is the non-dimensional mass function, which has the following definition:

$$M = \frac{m}{Le \rho D (S_h^* - S_l^*)} \quad (30)$$

The following partial differential equation for the mass function is obtained by manipulating Eqs. (28) and (29).

$$\frac{\partial^2 M}{\partial X^2} + \frac{\partial^2 M}{\partial Y^2} = \frac{\partial (US)}{\partial Y} - \frac{\partial (VS)}{\partial X} \quad (31)$$

By solving either Eq. (28), Eq. (29), or Eq. (31), we can obtain the dimensionless mass function M in the inner region of the rectangular enclosure under consideration. Masslines are created by drawing isolines of the mass function.

The following are the equivalent boundary conditions for the mass function M :

$$\begin{aligned} \text{for, } X = 0 \quad \text{and} \quad X = 1, \quad \frac{\partial M}{\partial X} &= 0, \\ \text{for, } Y = 0, \quad M &= 0, \\ \text{for, } Y = 1, \quad M &= \text{Sh}_{\text{avg}}, \end{aligned} \quad (32)$$

where Sh_{avg} is given by

$$\text{Sh}_{\text{avg}} = \int_0^1 \text{Sh} \, dY \quad (33)$$

and

$$\text{Sh} = - \left. \frac{\partial S}{\partial X} \right|_{X=0}. \quad (34)$$

3. Solution methodology

The flow governing equations are solved using the procedures below:

- Step 1: The finite difference method is used to discretize the governing Eqs. (7) to (10).
- Step 2: Iteratively solve the collection of discretized governing equations.
- Step 3: To compute the vorticity field in the computational domain, the vorticity equation Eq. (8) is solved first.
- Step 4: The stream function equation Eq. (7) is then solved using the Successive Over-Relaxation (SOR) method, and the velocity values are obtained after we have the stream function field.
- Step 5: The set of discretized equations for energy Eq. (9) and solute Eq. (10) transports in the computational domain are solved at the same time and utilize the new velocity values.
- Step 6: The algebraic equations obtained following the discretization procedure are solved using in-house computer code written in FORTRAN-95.
- Step 7: All dependent variables are assumed to be converged during the calculations if, and only if,

$$\left| \chi_{i,j}^{n+1} - \chi_{i,j}^n \right| \leq 10^{-7}, \quad (35)$$

where $\chi = (U, V, \Psi, \Omega, T, S)$, and (i, j) is the computation node point, and n is the iteration number.

4. Results and discussion

Figures 2 and 3 represent the effect of Rayleigh (Ra) and Hartmann (Ha) numbers on isotherms and heatlines. The top rows of both Figures 2 and 3 illustrate the isotherms for various Hartmann numbers ($0 \leq Ha \leq 8$). Even a minor increase in Ha causes a reduction in the temperature gradients on the vertical walls, resulting in the convection process dominated by conduction. The physics behind this is that electromagnetic force dominates the buoyancy force. It can also be noted that temperature gradients along the vertical walls rise as Ra strengthens from 5×10^3 to 5×10^4 . The reason behind this is that buoyancy force dominates viscous force, therefore the convection process enhances subsequently. It can also be observed that isotherms only represent spatial distribution of temperature along a particular isotherm line. Therefore, isotherms are unable to visualize the heat flow inside the enclosure and hence heatlines are required to do the task. The bottom rows of both Figures 2 and 3 illustrate the heatlines for various Hartmann numbers ($0 \leq Ha \leq 8$). Each heatline contour has two types of lines: one of these are starting from a higher temperature wall and reaches at lower temperature wall and has positive intensity and responsible for direct heat transfer whereas other heatlines form a loop and have negative intensity and are responsible for thermal mixing. In this way heatlines help in completing the visualization of heat flow. Furthermore, the direct heat transfer and thermal mixing are denoted by H_{\max} and H_{\min} . From Figures 2 and 3 and Table 1, as Ra increases from 5×10^3 to 5×10^4 , both H_{\max} and H_{\min} enhance. Subsequently, direct heat transfer and thermal mixing strengthen and hence significantly enhance in the convection process. However, magnitude of H_{\max} dominates the magnitude H_{\min} and hence thermal mixing is dominated by direct heat transfer. Furthermore, as Ha increases from 0 to 8, both the thermal mixing and direct heat transfer falls, but this fall is more for a lower Rayleigh number (Ra) in comparison to a higher Ra , and hence magnetic field is more effective for a lower Ra .

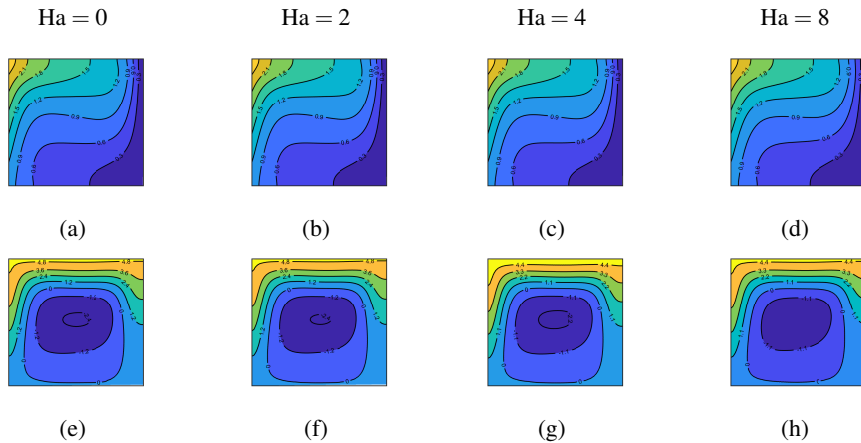


Fig. 2. Comparison of isotherms (T) (top row) and heatlines (H) (bottom row) for various Hartmann numbers (Ha) at $Ra = 5 \times 10^3$, $Le = 1$, and $N = 1$

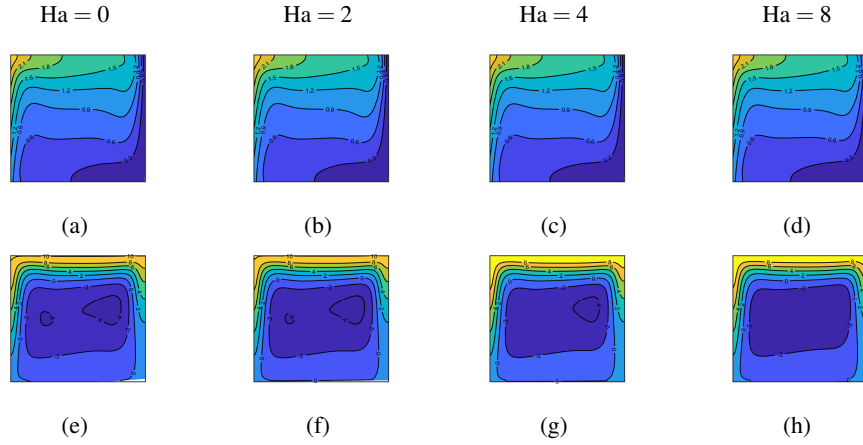


Fig. 3. Comparison of isotherms (T) (top row) and heatlines (H) (bottom row) for various Hartmann numbers (Ha) at $Ra = 5 \times 10^4$, $Le = 1$, and $N = 1$

Table 1. Comparison of thermal mixing and direct heat transfer

$Ra = 5 \times 10^3$				
Ha	H_{\min}	% change in H_{\min}	H_{\max}	% change in H_{\max}
0	-2.477		4.955	
2	-2.437	1.61	4.927	0.57
4	-2.325	4.60	4.845	1.66
8	-1.975	15.05	4.555	5.99
$Ra = 5 \times 10^4$				
0	-4.454		10.063	
2	-4.420	0.76	10.043	0.20
4	-4.325	2.15	9.983	0.59
8	-3.994	7.65	9.756	2.27

Figures 4 and 5 represent the effect of Rayleigh (Ra) and Hartmann (Ha) numbers on isoconcentrations and masslines. The top rows of both Figures 4 and 5 illustrate the isoconcentrations for various Hartmann numbers ($0 \leq Ha \leq 8$). Even a minor increase in Ha causes a reduction in the concentration gradients on the vertical walls, resulting in the convection process dominated by conduction. The physics behind this is that electromagnetic force dominates the concentration buoyancy force. It can also be noted that concentration gradients along the vertical walls rise as Ra is strengthened from 5×10^3 to 5×10^4 . The reason behind this is that concentration buoyancy force dominates viscous force, therefore convection process enhances subsequently. It can also be observed that isoconcentrations only represent spatial distribution of concentration along a particular isoconcentration line. Therefore, isoconcentrations are unable to visualize the mass flow inside the enclosure and hence masslines are required to do the task. The bottom rows of both Figures 4 and 5 illustrate the masslines for various Hartmann numbers ($0 \leq Ha \leq 8$).

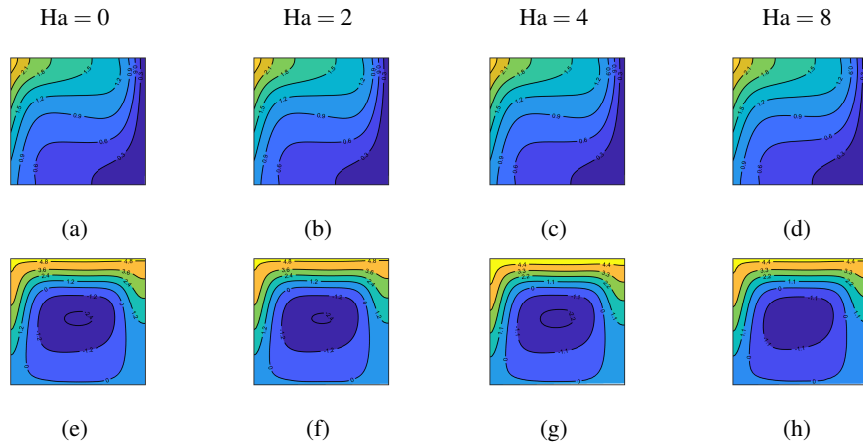


Fig. 4. Comparison of isoconcentration (S) (top row) and masslines (M) (bottom row) for various Hartmann numbers (Ha) at $Ra = 5 \times 10^3$, $Le = 1$, and $N = 1$

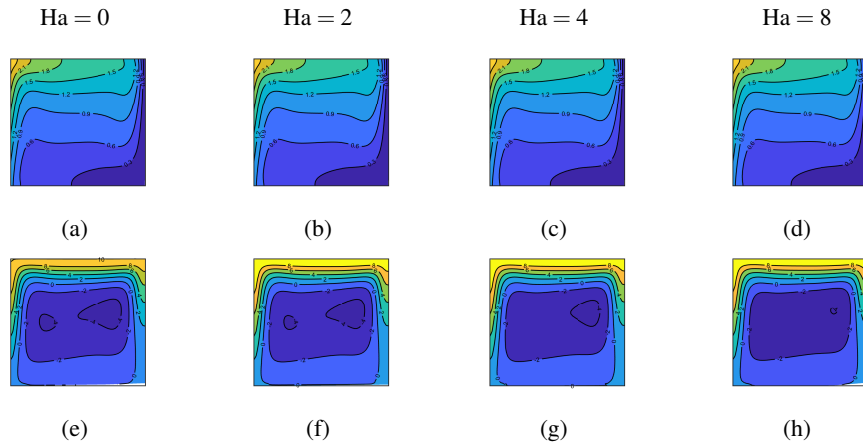


Fig. 5. Comparison of isoconcentration (S) (top row) and masslines (M) (bottom row) for various Hartmann numbers (Ha) at $Ra = 5 \times 10^4$, $Le = 1$, and $N = 1$

Each massline contour has two types of lines: one of these are starting from higher concentration wall and reaches at a lower concentration wall and has positive intensity and responsible for direct mass transfer whereas other masslines form a loop and have negative intensity and are responsible for solute mixing. In this way masslines help in the complete visualizing of mass flow. Furthermore, the direct mass transfer and solute mixing are denoted by M_{\max} and M_{\min} . From Figures 4 and 5, as Ra increases from 5×10^3 to 5×10^4 , both M_{\max} and M_{\min} enhance. Subsequently, direct mass transfer and solute mixing strengthen and hence significantly enhance in convection process. But magnitude of M_{\max} dominates the magnitude M_{\min} and hence solute mixing is dominated by direct mass transfer. Furthermore, as Ha increases from 0 to 8, both the solute mixing and direct mass transfer falls but this fall is more

for lower Rayleigh number (Ra) in comparison to higher Ra and hence magnetic field is more effective for lower Ra.

Table 2. Comparison of solutal mixing and direct solute transfer

Ra = 5×10^3				
Ha	M_{\min}	% change in M_{\min}	M_{\max}	% change in M_{\max}
0	-2.481		4.946	
2	-2.441	1.61	4.918	0.57
4	-2.329	4.59	4.836	1.67
8	-1.979	15.03	4.547	5.98
Ra = 5×10^4				
0	-4.478		10.012	
2	-4.445	0.74	9.992	0.20
4	-4.349	2.16	9.932	0.59
8	-4.018	7.61	9.707	2.27

4.1. Overall heat and mass transfer

The average Nusselt and average Sherwood numbers are used to represent overall heat and mass transfers, and are denoted by Nu_{avg} and Sh_{avg} , respectively. Table 3 compares overall heat and mass transfer for different Rayleigh (Ra) and Hartmann (Ha) numbers, respectively. It can be seen that when Ra increases from 5×10^3 to 5×10^4 , the overall heat and mass transfer doubles, or there is a 100% increment. It is also worth noting that the Hartmann number (Ha) is more effective for lower Ra than for higher Ra. For higher Hartmann ($Ha = 8$), there is a maximum reduction in overall heat and mass transfer.

Table 3. Comparison of overall heat and mass transfer

Ra = 5×10^3				
Ha	Nu_{avg}	% change in Nu_{avg}	Sh_{avg}	% change in Sh_{avg}
0	4.962		4.953	
2	4.934	0.57	4.925	0.57
4	4.852	1.66	4.843	1.66
8	4.562	5.99	4.553	5.99
Ra = 5×10^4				
0	10.077		10.026	
2	10.057	0.20	10.006	0.20
4	9.997	0.59	9.947	0.59
8	9.770	2.28	9.721	2.27

5. Concluding remarks

The current research focuses on employing heat and mass lines approaches to visualize the heat and mass flows in MHD thermo-diffusion convection in an enclosure. Heat and mass flows inside the enclosure are best understood using heat and mass lines visualization techniques over isotherms and isoconcentrations. Overall, because of the dominance of buoyant force over viscous force as the Rayleigh number rises, heat and mass transmission from higher temperature and concentration walls to the fluid improves. Even a minor increase in the Hartmann number Ha results in a significant reduction in overall heat and mass fluxes. Furthermore, the reduction for smaller Rayleigh numbers Ra outweighs the reduction for larger Rayleigh numbers Ra . The largest reduction in overall heat and mass transport has been observed for greater Hartmann ($Ha = 8$). As a result, we can control heat and mass transfer by applying proper magnetic field strength.

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