

## THE STABILITY CONDITIONS OF THE CUBIC DAMPING VAN DER POL-DUFFING OSCILLATOR USING THE HPM WITH THE FREQUENCY-EXPANSION TECHNOLOGY

*Yusry O. El-Dib*

*Department of Mathematics, Faculty of Education  
Ain Shams University, Roxy, Cairo, Egypt  
yusryeldib52@hotmail.com*

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**Abstract.** In this paper, we perform the frequency-expansion formula for the nonlinear cubic damping van der Pol's equation, and the nonlinear frequency is derived. Stability conditions are performed, for the first time ever, by the nonlinear frequency technology and for the nonlinear oscillator. In terms of the van der Pol's coefficients the stability conditions have been performed. Further, the stability conditions are performed in the case of the complex damping coefficients. Moreover, the study has been extended to include the influence of a forcing van der Pol' oscillator. Stability conditions have been derived at each resonance case. Redoing the perturbation theory for the van der Pol oscillator illustrates more of a resonance formulation such as sub-harmonic resonance and super-harmonic resonance. More approximate nonlinear dispersion relations of quartic and quintic forms in the squaring of the extended frequency are derived, respectively.

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### 1. Introduction

In the present paper, the stability criteria for the dynamics of a Van der Pol-Duffing oscillator are considered. This equation is one of the most interesting and important collective behaviors in non-linear dynamics. Many efforts have been made to approximate the solutions of this equation or to construct simple maps that qualitatively describe important features of the dynamics. The solutions of this equation are oscillations, which may have periodic forms or non-periodic, as well. We can mark off two cases: the unforced, which is autonomous (there is no excitation parameter) and the forced oscillator with excitation frequency, which is non-autonomous.

In recent years, several analytical methods such as homotopy perturbation [1], harmonic balance [2], residue harmonic balance [3], The Hamiltonian approach [4],

homotopy analysis [5], max-min approach [6], coupling of homotopy variation [7], iterative homotopy harmonic balance method [8], global residue harmonic balance [9], Fourier series solutions with finite harmonic terms [10], amplitude-frequency formulation [11-13], parameter-expansion method [14-19], multi-step homotopy analysis method [20], multiple-scales homotopy perturbation method [21-23] and the Frobenius-homotopy method [24] have been developed for solving strongly nonlinear oscillators.

The system considered herein is an extended version of the well-known of the typical van der Pol' oscillator, which is a paradigmatic model for the description of self-excited oscillations. Adding a cubic nonlinearity to the primary system, it is possible to obtain a large variation frequency [25]. This modified system is usually referred to as van der Pol-Duffing oscillator [26]. The Van der Pol-Duffing forced oscillator with the variation of the forced frequency are obtained and studied, based on the homotopy analysis method, by Jifeng Cui et al. [27]. In this work, the stability of the periodic solutions is obtained by use of Floquet theory.

The main idea of this work is to obtain the stability criterion for the generalized van der Pol-Duffing oscillator and to find approximate periodic solutions. In Ref. [18-20] the author has established the periodic solution and studied the stability behavior via the multiple-scales homotopy technique. Stability criteria have been established from the linear perturbation of the amplitude equation around the steady-state solution. In the present work, a new method is adopted to construct the stability criterion. The criterion has been established, for the first-time, via the homotopy frequency analysis. The derived of the nonlinear frequency proposed by scientists and engineers [14-18, 26] is the most effective and convenient method for handling nonlinear problems. In this method, the solution and unknown frequency of oscillation are expanding in a series by a bookkeeping parameter. The use of the nonlinear frequency in studying the stability behavior is a new tool that is important and powerful for solving nonlinear oscillator systems arising in nonlinear science and engineering.

## 2. Frequency analysis via homotopy perturbation method for the autonomous case

We consider the following equation, which is a generalization of cubic van der Pol's-Duffing equation:

$$\ddot{y} + a_1\dot{y} + \omega_0^2 y + Qy^3 + a_2y^2\dot{y} + a_3y\dot{y}^2 + a_4\dot{y}^3 = 0 \quad (1)$$

where  $y = y(t)$ , and  $t$  is the independent variable with the initial conditions  $y(0) = A$ ;  $\dot{y}(0) = 0$ . The constants  $\omega_0^2$  and  $Q$  are real. The remaining coefficients  $a_j$ ;  $j = 1:4$  are, in general, complex constants. In order to solve this equation via the homotopy perturbation technique, we define the two parts

$$L(y(t)) = \ddot{y} + \omega_0^2 y \quad \text{and} \quad (2)$$

$$N(y(t)) = a_1 \dot{y} + Qy^3 + a_2 y^2 \dot{y} + a_3 y \dot{y}^2 + a_4 \dot{y}^3. \quad (3)$$

Construct the homotopy equation in the form

$$L(y(t; \rho)) + \rho N(y(t; \rho)) = 0; \quad \rho \in [0, 1] \quad (4)$$

Considering the frequency analysis so that we define the following frequency expansion:

$$\omega^2 = \omega_0^2 + \rho \omega_1 + \rho^2 \omega_2 + \dots \quad (5)$$

Assuming that the function  $y(t; \rho)$  has been expanded as

$$y(t; \rho) = y_0(t) + \rho y_1(t) + \rho^2 y_2(t) + \dots \quad (6)$$

Employing (5) and (6) with (4), equating the identical powers of  $\rho$  to zero, yields

$$\rho^0: \ddot{y}_0 + \omega^2 y_0 = 0, \quad y_0(0) = A, \quad \dot{y}_0(0) = 0, \quad (7)$$

$$\rho^1: \ddot{y}_1 + \omega^2 y_1 = \omega_1 y_0 - a_1 \dot{y}_0 - Qy_0^3 - a_2 y_0^2 \dot{y}_0 - a_3 y_0 \dot{y}_0^2 - a_4 \dot{y}_0^3, \quad y_1(0) = 0, \quad \dot{y}_1(0) = 0. \quad (8)$$

The solution of the zero-order problem leads to

$$y_0(t) = A \cos \omega t. \quad (9)$$

Substituting (9) into (8), the requirement of no secular term in  $y_1(t)$  needs

$$\omega_1 = \frac{1}{4} A^2 (3Q + a_3 \omega^2) \quad \text{and} \quad (10)$$

$$A^2 = -\frac{4a_1}{a_2 + 3a_4 \omega^2}. \quad (11)$$

The solution of (8) without secular terms yields

$$y_1(t) = \frac{Aa_1}{8\omega^2(a_2 + 3a_4\omega^2)} \left[ (a_3\omega^2 - Q)(\cos 3\omega t - \cos \omega t) + \omega(a_2 - a_4\omega^2)(\sin 3\omega t - 3\sin \omega t) \right], \quad (12)$$

where  $A^2$  has been replaced by (11). If the first order approximation is enough, then setting  $\rho \rightarrow 1$  into expansion (6) the approximate periodic solution can be readily obtained:

$$y(t) = A \cos \omega t + \frac{Aa_1}{8\omega^2(a_2 + 3a_4\omega^2)} \left[ \begin{aligned} &(a_3\omega^2 - Q)(\cos 3\omega t - \cos \omega t) \\ &+ \omega(a_2 - a_4\omega^2)(\sin 3\omega t - 3\sin \omega t) \end{aligned} \right]. \quad (13)$$

The approximate solution (13) is an oscillator where the parameter  $\omega$  has real values. This requires formulating a dispersion relation including the argument  $\omega$ .

### 2.1. Stability conditions of cubic damping van der Pol's nonlinear oscillator

In order to find the expression for the nonlinear frequency  $\omega^2$ , we substitute (10) into (5) and setting  $\rho \rightarrow 1$  yields the approximate nonlinear frequency, in terms of the amplitude  $A$ , in the form

$$\omega^2 = \frac{\omega_0^2 + \frac{3}{4}QA^2}{1 - \frac{1}{4}a_3A^2}. \quad (14)$$

Removing the amplitude  $A^2$  from (14) using (11) leads to

$$3a_4\omega^4 - (3\omega_0^2a_4 - a_2 - a_1a_3)\omega^2 + 3a_1Q - \omega_0^2a_2 = 0. \quad (15)$$

The necessary and sufficient condition for stability is that  $\omega$  must be a real quantity. This constrains for stability can be achieved when the following conditions on (15) are satisfied together:

$$\begin{aligned} a_4 > 0, \quad (3\omega_0^2a_4 - a_1a_3 - a_2) > 0, \quad (3a_1Q - \omega_0^2a_2) > 0, \quad \text{and} \\ (3\omega_0^2a_4 - a_1a_3 - a_2)^2 + 12a_4(\omega_0^2a_2 - 3a_1Q) > 0. \end{aligned} \quad (16)$$

These are the required conditions in order to obtain the oscillatory solution.

In order to find the necessary and sufficient conditions for the existing the limit cycle, we remove  $\omega^2$  from (11) using (14) yields

$$(9a_4Q - a_2a_3)A^4 + 4(3a_4\omega_0^2 + a_2 - a_1a_3)A^2 + 16a_1 = 0. \quad (17)$$

According to this approximate analysis, a limit cycle will exist if the amplitude  $A$  is real. This requires the following relations:

$$\begin{aligned} a_1 > 0, \quad 9a_4Q - a_2a_3 > 0, \quad 3a_4\omega_0^2 + a_2 - a_1a_3 < 0, \quad \text{and} \\ (3a_4\omega_0^2 + a_2 - a_1a_3)^2 - 4a_1(9a_4Q - a_2a_3) > 0. \end{aligned} \quad (18)$$

In fluid mechanics, the damping coefficients  $a_1, a_2, a_3$  and  $a_4$  may appear in the complex form. In order to obtain the stability criteria, in this case, one can

assume that  $\omega^2$  be real in the characteristic equation (15) separating the real and imaginary parts then employing the imaginary part to the real part. The result represents a characteristic equation having real coefficients. Therefore, for the oscillatory solution, the requirement of  $\omega$  being real yields the following stability conditions:

$$\begin{aligned} \operatorname{Re} a_1 > 0, \operatorname{Re} [3\omega_0^2 a_4 \bar{a}_4 a_1 - a_1 \bar{a}_1 a_3 \bar{a}_4] - (\operatorname{Re} a_4)(\operatorname{Re} a_1 \bar{a}_2) + (\operatorname{Im} a_4)(\operatorname{Im} a_1 \bar{a}_2) > 0, \text{ and} \\ (3Q - \omega_0^2) a_1 \bar{a}_1 (\operatorname{Re} a_4) - \omega_0^2 (\operatorname{Im} a_4)(\operatorname{Im} a_1 a_2) > 0. \end{aligned} \tag{19}$$

### 3. The non-autonomous case

We are now concerned with the excited, by a periodic external force, van der Pol-Duffing oscillator. This is the more general case, so we rewrite equation (1) with the forcing part included in

$$\ddot{y} + a_1 \dot{y} + \omega_0^2 y + Qy^3 + a_2 y^2 \dot{y} + a_3 y \dot{y}^2 + a_4 \dot{y}^3 = Bf \cos \Omega t, \quad y(0) = B; \quad \dot{y}(0) = 0. \tag{20}$$

where  $f$  and  $\Omega$  represent the amplitude and the frequency of the forcing part. The application of the homotopy perturbation method allows several types for the primary part  $L(y(t))$ . The chosen of  $L(y(t))$  as defined by (2) will leads to study the stability of the harmonic resonance case. Some changes in the homotopy equation (4) is done whenever the alternative choice for the primary part  $L(y(t))$  of (20) is included the forcing part. This case will lead to obtain the stability criteria at sub-harmonic and super-harmonic resonance cases. These are the subject of the next sections.

#### 3.1. Solution and stability conditions at the harmonic resonance case

We proceed as in the previous sections assuming that the homotopy equation has been built in the following form:

$$\ddot{y} + \omega_0^2 y + \rho(a_1 \dot{y} + Qy^3 + a_2 y^2 \dot{y} + a_3 y \dot{y}^2 + a_4 \dot{y}^3 - Bf \cos \Omega t) = 0. \tag{21}$$

To discuss the exact resonance case, we assume that the frequency of the periodic force  $\Omega$  is equivalent to the nonlinear frequency  $\omega$ . The requirements of obtaining the uniform solution at the resonance case lead to the removal of the terms that producing secularity in the first-order problem of (21), so we obtain

$$\Omega_1 = \frac{1}{4} B^2 (3Q + a_3 \Omega^2) - f \quad \text{and} \quad B^2 = -\frac{4a_1}{a_2 + 3a_4 \Omega^2}. \tag{22}$$

The function of  $y_1(t)$  without secular terms has the form

$$y_1(t) = \frac{Ba_1}{8\Omega^2(a_2 + 3a_4\Omega^2)} \left[ \begin{aligned} &(a_3\Omega^2 - Q)(\cos 3\Omega t - \cos \Omega t) \\ &+ \Omega(a_2 - a_4\Omega^2)(\sin 3\Omega t - 3\sin \Omega t) \end{aligned} \right], \quad (23)$$

The first order approximate solution of the harmonic resonance case has the form

$$y(t) = B \cos \Omega t + \frac{Ba_1}{8\Omega^2(a_2 + 3a_4\Omega^2)} \left[ \begin{aligned} &(a_3\Omega^2 - Q)(\cos 3\Omega t - \cos \Omega t) \\ &+ \Omega(a_2 - a_4\Omega^2)(\sin 3\Omega t - 3\sin \Omega t) \end{aligned} \right]. \quad (24)$$

In this case, the frequency  $\Omega$  has satisfied the following dispersion relation:

$$3a_4\Omega^4 - (3a_4\omega_0^2 - a_2 - a_1a_3 - 3a_4f)\Omega^2 + (3Qa_1 - \omega_0^2a_2 + a_2f) = 0. \quad (25)$$

Since the forcing frequency  $\Omega$  is real, then the necessary and sufficient stability conditions are

$$a_2 > 0, \quad a_4 > 0, \quad f < \omega_0^2 - \frac{a_1a_3 + a_2}{3a_4}, \quad \text{and} \quad f > \omega_0^2 - 3Q\frac{a_1}{a_2}. \quad (26)$$

These stability criteria occur for the system having real coefficients of the van der Pol-Duffing equation (21). Further, when these coefficients are in complex form, the stability conditions are present in the form

$$\begin{aligned} &\text{Re } a_4 > 0, \quad \text{Re} [a_4\bar{a}_4(3(\omega_0^2 - f)a_4 - a_1a_3) - a_2\bar{a}_4] + (\text{Im } a_4)(\text{Im } a_2\bar{a}_4) > 0, \quad \text{and} \\ &(\text{Re } a_4)\text{Re} [3Qa_1\bar{a}_4 - (\omega_0^2 - f)a_2\bar{a}_4] - (\text{Im } a_4)\text{Im} [3Qa_1\bar{a}_4 - (\omega_0^2 - f)(a_2\bar{a}_4)] > 0. \end{aligned} \quad (27)$$

#### 4. Further harmonic resonance cases for the non-autonomous problem

In the application of the homotopy perturbation method, for the forcing van der Pol's damping nonlinear oscillator (20), there is another chosen for the primary part  $L(y(t))$ . The alternative is chosen [22] such that

$$L(y(t)) = \ddot{y} + \omega_0^2 y - Bf \cos \Omega t, \quad (28)$$

Redoing the homotopy perturbation method using the primary operator (28) leads to rearranging the homotopy equation (21) to become

$$\ddot{y} + \omega_0^2 y - Bf \cos \Omega t + \rho(a_1\dot{y} + Qy^3 + a_2y^2\dot{y} + a_3y\dot{y}^2 + a_4\dot{y}^3) = 0. \quad (29)$$

Employing the two expansions (5) and (6), assuming that  $\Omega \neq \omega$ , the primary solution becomes

$$y_0(t) = B \left( 1 - \frac{f}{\omega^2 - \Omega^2} \right) \cos \omega t + \frac{Bf}{\omega^2 - \Omega^2} \cos \Omega t. \quad (30)$$

We briefly now present the behavior of the equation (29) using a first-order approximation. Accordingly, the first-order perturbation is performed as

$$\begin{aligned} \ddot{y}_1 + \omega^2 y_1 = & B \left( 1 - \frac{f}{\omega^2 - \Omega^2} \right) \left\{ \omega_1 - \frac{1}{4} \left[ (a_3 \omega^2 + 3Q) \left( 1 - \frac{f}{\omega^2 - \Omega^2} \right)^2 + 2(a_3 \Omega^2 + 3Q) \frac{f^2}{(\omega^2 - \Omega^2)^2} \right] B^2 \right\} \cos \omega t \\ & + \omega B \left( 1 - \frac{f}{\omega^2 - \Omega^2} \right) \left\{ a_1 + \frac{1}{4} B^2 \left[ (a_2 + 3a_4 \omega^2) \left( 1 - \frac{f}{\omega^2 - \Omega^2} \right)^2 + 2(a_2 + 3a_4 \Omega^2) \frac{f^2}{(\omega^2 - \Omega^2)^2} \right] \right\} \sin \omega t \\ & + B \left( \frac{f}{\omega^2 - \Omega^2} \right) \left\{ \omega_1 - \frac{1}{4} (3Q + \Omega^2 a_3) B^2 \left( \frac{f}{\omega^2 - \Omega^2} \right)^2 - \frac{1}{2} (3Q + \omega^2 a_3) B^2 \left( 1 - \frac{f}{\omega^2 - \Omega^2} \right)^2 \right\} \cos \Omega t \\ & + \Omega B \left( \frac{f}{\omega^2 - \Omega^2} \right) \left\{ a_1 + \frac{1}{2} (a_2 + 3\omega^2 a_4) B^2 \left( 1 - \frac{f}{\omega^2 - \Omega^2} \right)^2 + \frac{1}{4} (a_2 + 3a_4 \Omega^2) B^2 \left( \frac{f}{\omega^2 - \Omega^2} \right)^2 \right\} \sin \Omega t \\ & + \frac{1}{4} B^3 \left( 1 - \frac{f}{\omega^2 - \Omega^2} \right)^3 \left[ (a_3 \omega^2 - Q) \cos 3\omega t + \omega (a_2 - a_4 \omega^2) \sin 3\omega t \right] \\ & + \frac{1}{4} B^3 \left( \frac{f}{\omega^2 - \Omega^2} \right)^3 \left[ (\Omega^2 a_3 - Q) \cos 3\Omega t + \Omega (a_2 - \Omega^2 a_4) \sin 3\Omega t \right] \\ & + \frac{1}{4} B^3 \left( \frac{f}{\omega^2 - \Omega^2} \right) \left( 1 - \frac{f}{\omega^2 - \Omega^2} \right)^2 \\ & \quad \times \left\{ \begin{aligned} & [a_3 a_3 (2\Omega + \omega) - 3Q] \cos(\Omega + 2\omega)t - [a_3 \omega (2\Omega - \omega) + 3Q] \cos(\Omega - 2\omega)t \\ & + [a_2 (\Omega + 2\omega) - 3\Omega \omega^2 a_4] \sin(\Omega + 2\omega)t + [a_2 (\Omega - 2\omega) - 3\Omega \omega^2 a_4] \sin(\Omega - 2\omega)t \end{aligned} \right\} + \\ & + \frac{1}{4} B^3 \left( \frac{f}{\omega^2 - \Omega^2} \right)^2 \left( 1 - \frac{f}{\omega^2 - \Omega^2} \right) \times \\ & \quad \times \left\{ \begin{aligned} & [a_3 \Omega (\Omega + 2\omega) - 3Q] \cos(2\Omega + \omega)t + [a_3 \Omega (\Omega - 2\omega) - 3Q] \cos(2\Omega - \omega)t \\ & + [a_2 (2\Omega + \omega) + 3\Omega^2 \omega a_4] \sin(2\Omega + \omega)t + [a_2 (2\Omega - \omega) - 3\Omega^2 \omega a_4] \sin(2\Omega - \omega)t \end{aligned} \right\}. \end{aligned} \quad (31)$$

Three cases can be distinguished in analyzing this case. The non-resonance case, where the forcing frequency  $\Omega$  is away from the nonlinear frequency  $\omega$ , the sub-harmonic resonance case, which occurs as  $\Omega = 3\omega$  and the super-harmonic resonance case which arises whence  $\Omega = \frac{1}{3}\omega$ .

#### 4.1. The non-resonance case

In this case, the uniform solution for (31) is performed when the terms that producing secular terms absent. At this stage, we add the solution of (31) without secular terms to the primary solution (30) to produce the final first-order approximate solution in the form

$$\begin{aligned}
 y(t) = & B \left( 1 - \frac{f}{\omega^2 - \Omega^2} + \frac{B^2}{4(\omega^2 - \Omega^2)^3} \alpha \right) \cos \omega t + \frac{B^3}{4\omega(\omega^2 - \Omega^2)^3} \beta \sin \omega t \\
 & + \frac{Bf}{(\omega^2 - \Omega^2)} \left\{ 1 + \frac{B^2}{4(\omega^2 - \Omega^2)^3} \left[ -(3Q + \omega^2 a_3)(\omega^2 - \Omega^2 - f)^2 + f^2(a_3 \Omega^2 + 3Q) \right] \right\} \cos \Omega t \\
 & - \frac{B^3 \Omega f}{4(\omega^2 - \Omega^2)^4} \left[ f^2(a_2 + 3a_4 \Omega^2) + \frac{1}{2}(a_2 + 3\omega^2 a_4)(\omega^2 - \Omega^2 - f)^2 \right] \sin \Omega t \\
 & - \frac{B^3}{32\omega^2(\omega^2 - \Omega^2)^3} (\omega^2 - \Omega^2 - f)^3 \left[ (a_3 \omega^2 - Q) \cos 3\omega t + \omega(a_2 - a_4 \omega^2) \sin 3\omega t \right] \\
 & + \frac{B^3 f^3}{4(\omega^2 - 9\Omega^2)(\omega^2 - \Omega^2)^3} \left[ (\Omega^2 a_3 - Q) \cos 3\Omega t + \Omega(a_2 - \Omega^2 a_4) \sin 3\Omega t \right] \\
 & + \frac{B^3 f(\omega^2 - \Omega^2 - f)^2}{4(\omega^2 - \Omega^2)^3} \left[ \frac{3Q - \omega a_3(2\Omega + \omega)}{(\Omega + \omega)(\Omega + 3\omega)} \cos(\Omega + 2\omega)t + \frac{a_3 \omega(2\Omega - \omega) + 3Q}{(\Omega - \omega)(\Omega - 3\omega)} \cos(\Omega - 2\omega)t \right] \\
 & + \frac{B^3 f(\omega^2 - \Omega^2 - f)^2}{4(\omega^2 - \Omega^2)^3} \left[ \frac{3\Omega \omega^2 a_4 - a_2(\Omega + 2\omega)}{(\Omega + \omega)(\Omega + 3\omega)} \sin(\Omega + 2\omega)t + \frac{3\Omega \omega^2 a_4 - a_2(\Omega - 2\omega)}{(\Omega - \omega)(\Omega - 3\omega)} \sin(\Omega - 2\omega)t \right] \\
 & + \frac{B^3 f^2(\omega^2 - \Omega^2 - f)}{16\Omega(\omega^2 - \Omega^2)^3} \left[ \frac{3Q - a_3 \Omega(\Omega + 2\omega)}{\Omega + \omega} \cos(2\Omega + \omega)t + \frac{3Q - a_3 \Omega(\Omega - 2\omega)}{\Omega - \omega} \cos(2\Omega - \omega)t \right] \\
 & - \frac{B^3 f^2(\omega^2 - \Omega^2 - f)}{16\Omega(\omega^2 - \Omega^2)^3} \left[ \frac{a_2(2\Omega + \omega) + 3\Omega^2 \omega a_4}{\Omega + \omega} \sin(2\Omega + \omega)t - \frac{3\Omega^2 \omega a_4 - a_2(2\Omega - \omega)}{\Omega - \omega} \sin(2\Omega - \omega)t \right],
 \end{aligned} \tag{32}$$

where the constants  $\alpha$  and  $\beta$  are

$$\begin{aligned}
 \alpha = & \frac{(\omega^2 - \Omega^2 - f)^3}{8\omega^2} (a_3 \omega^2 - Q) + \frac{3f(\omega^2 - \Omega^2 - f)^2}{(9\omega^2 - \Omega^2)} (3Q + 5a_3 \omega^2) \\
 & + \frac{f^2(\omega^2 - \Omega^2 - f)}{2(\omega^2 - \Omega^2)} \left[ 3Q + a_3(2\omega^2 - \Omega^2) \right] + \frac{4f^3 \left[ 2\Omega^4 a_3 - Q(\omega^2 - 7\Omega^2) \right]}{(\omega^2 - \Omega^2)(\omega^2 - 9\Omega^2)},
 \end{aligned} \tag{33}$$



$$\beta = \frac{3f^3(\omega^2 - \Omega^2 - f)^3}{8}(a_2 - a_4\omega^2) - \frac{2\Omega^2 f^3}{(\omega^2 - 9\Omega^2)(\omega^2 - \Omega^2)} [a_2(\omega^2 + 3\Omega^2) - 3a_4\Omega^2(\omega^2 - 5\Omega^2) +]$$

$$- \frac{f(\omega^2 - \Omega^2 - f)^2}{2(\omega^2 - \Omega^2)(9\omega^2 - \Omega^2)} [a_2(48\omega^4 - 45\Omega^2\omega^2 + 5\Omega^4) + 3a_4\Omega^2\omega^2(11\omega^2 - 3\Omega^2)]$$

$$- \frac{f^2(\omega^2 - \Omega^2 - f)}{4\Omega(\omega^2 - \Omega^2)} [a_2(3\omega^3 - 15\omega^2\Omega + 20\Omega^3) + 3\Omega^2\omega a_4(3\omega^2 - 5\omega\Omega - 6\Omega^3)]. \quad (34)$$

As explained before, the result of removing the secular terms from equation (31) implied

$$\omega_1 = \frac{B^2}{4(\omega^2 - \Omega^2)^2} [(3Q + a_3\omega^2)(\omega^2 - \Omega^2)(\omega^2 - \Omega^2 - 2f) + 9Qf^2 + a_3f^2(\omega^2 + 2\Omega^2)], \quad (35)$$

$$B^2 = - \frac{4(\omega^2 - \Omega^2)^2 a_1}{(a_2 + 3\omega^2 a_4)(\omega^2 - \Omega^2)(\omega^2 - \Omega^2 - 2f) + 3a_2 f^2 + 3a_4 f^2(\omega^2 + 2\Omega^2)}. \quad (36)$$

The above solvability conditions used to formulate the following nonlinear frequency that corresponds to the non-resonance case:

$$\omega^8 + m_3\omega^6 + m_2\omega^4 + m_1\omega^2 + m_0 = 0, \quad (37)$$

where the constants  $m$ 's are:

$$m_3 = \frac{1}{3a_4} (a_2 + a_1 a_3 - 3a_4 \omega_0^2 - 6a_4 (f + \Omega^2)),$$

$$m_2 = \frac{1}{3a_4} [3a_4 (f + \Omega^2)^2 + 2(3a_4 \omega_0^2 - a_1 a_3 - a_2)(f + \Omega^2) + 3a_1 Q - a_2 \omega_0^2],$$

$$m_1 = \frac{1}{3a_4} [(a_1 a_3 - 3a_4 \omega_0^2)(f + \Omega^2)^2 + (2a_2 \omega_0^2 - 6a_1 Q)(f + \Omega^2) + a_2(3f^2 + 2f\Omega^2 + \Omega^4) + 6a_4 f^2 \Omega^2], \quad (38)$$

$$m_0 = \frac{1}{3a_4} [(3a_1 Q - a_2 \omega_0^2)(3f^2 + 2f\Omega^2 + \Omega^4) + 2(a_1 a_3 - 3a_4 \omega_0^2) f^2 \Omega^2].$$

The requirement of all the eigenvalues for the characteristic equation (37) to be real needs all the four roots of (37) must be positive and real. From elementary algebra, the four roots are positive whence

$$m_3 < 0, m_2 > 0, m_1 < 0 \text{ and } m_0 > 0. \quad (39)$$

There are three discriminants for the quartic polynomial to ensure the existences of the real roots [28]. The necessary and sufficient conditions, for all the eigen-values of (37) to be real, are

$$3m_1^2 - 8m_0m_2 \geq 0, \quad 4m_2^2 - 9m_1m_3 \geq 0, \quad 3m_3^2 - 8m_2 \geq 0. \quad (40)$$

Conditions (39) and conditions (40) together represent the strict requirements to obtain the periodic solution.

#### 4.2. The sub-harmonic resonance case

The sub-harmonic resonance case arises when the frequency  $\Omega$  has equivalent to  $3\omega$ . In order to obtain periodic solutions and to study the stability behavior at this resonance case, we need to remove the additional secular terms that are found in equation (31). Removing of these secularity leads to formulate the approximate nonlinear frequency, which satisfied the following characteristic equation:

$$\omega^8 + k_3\omega^6 + k_2\omega^4 + k_1\omega^2 + k_0 = 0, \quad (41)$$

where  $k$ 's are real constants listed below:

$$\begin{aligned} k_3 &= \frac{1}{24a_4} (8a_2 + 8a_1a_3 + 15a_4f - 24a_4\omega_0^2), \\ k_2 &= \frac{1}{96a_4} [4a_2(f - 8\omega_0^2) + 3a_4f(11f - 20\omega_0^2) + 12a_1(8Q - a_3f)], \\ k_1 &= \frac{f}{96a_4} [a_2(f - 4\omega_0^2) - 33a_4f\omega_0^2 + 7a_1a_3f + 12a_1Q], \\ k_0 &= \frac{f^2}{96a_4} (3Qa_1 - a_2\omega_0^2). \end{aligned} \quad (42)$$

Accordingly, the uniform approximate first order solution has the final form:

$$\begin{aligned} y(t) &= \frac{B^3}{512 \times 240\omega^8} \left[ \begin{aligned} &6Q(2f^3 + 65f^2\omega^2 + 80f\omega^4 - 640\omega^6) \\ &+ a_3\omega^2(-13f^3 + 530f^2\omega^2 + 800f\omega^4 + 3840\omega^6) \end{aligned} \right] \cos \omega t \\ &+ \frac{B^3}{512 \times 240\omega^7} \left[ \begin{aligned} &2a_2(2f^3 + 545f^2\omega^2 + 2000f\omega^4 - 5760\omega^6) \\ &+ 9a_4\omega^2(-289f^3 - 410f^2\omega^2 + 1120f\omega^4 + 1280\omega^6) \end{aligned} \right] \sin \omega t \\ &- \frac{B^3}{8192\omega^8} \left[ \begin{aligned} &Q(f^3 + 24f^2\omega^2 - 256\omega^6) - a_3\omega^2(f^3 + 40f^2\omega^2 - 128f\omega^4 - 256\omega^6) \end{aligned} \right] \cos 3\omega t \\ &+ \frac{B^3}{8192\omega^7} \left[ \begin{aligned} &a_2(f^3 + 24f^2\omega^2 - 256\omega^6) - a_4\omega^2(49f^3 + 24f^2\omega^2 - 384f\omega^4 - 256\omega^6) \end{aligned} \right] \sin 3\omega t \end{aligned}$$

$$\begin{aligned}
 & -\frac{B^3}{128 \times 96} f(f+8\omega^2) [6Q - a_3(f+14\omega^2)] \cos 5\omega t \\
 & -\frac{B^3}{96 \times 256\omega^7} f(8\omega^2+f) [5a_2(f-4\omega^2) + 36\omega^2 a_4(\omega^2-f)] \sin 5\omega t \\
 & -\frac{B^3}{192 \times 512\omega^8} f^2(8\omega^2+f) [3(5a_3\omega^2-Q)\cos 7\omega t + \omega(7a_2+27\omega^2 a_4)\sin 7\omega t] \\
 & +\frac{B^3}{320 \times 512\omega^8} f [(9\omega^2 a_3-Q)\cos 9\omega t + 3\omega(a_2-9\omega^2 a_4)\sin 9\omega t],
 \end{aligned} \tag{43}$$

where the amplitude  $B$  in this case has the form

$$B^2 = -\frac{128\omega^4 a_1}{a_2(f^2+4f\omega^2+32\omega^4)+3a_4\omega^2(11f^2+20f\omega^2+32\omega^4)}. \tag{44}$$

As mentioned before, the stability conditions are derived in the form

$$\begin{aligned}
 & k_3 < 0, \quad k_2 > 0, \quad k_1 > 0, \quad k_0 > 0, \quad \text{and} \\
 & 3k_1^2 - 8k_0k_2 \geq 0, \quad 4k_2^2 - 9k_1k_3 \geq 0, \quad 3k_3^2 - 8k_2k_4 \geq 0.
 \end{aligned} \tag{45}$$

### 4.3. The super-harmonic resonance case

When the frequency  $\Omega$  has equivalent to  $\frac{1}{3}\omega$ , then we have the so-called the super-harmonic resonance case. The first-order approximate solution of the forcing van der Pol-Duffing equation (20), without secular terms, is formulated in the following form:

$$\begin{aligned}
 y(t) = & \frac{Bf}{16 \times 64\Omega^6(f-8\Omega^2)} \left[ \begin{aligned} & 128\Omega^4(f-8\Omega^2) + B^2Q(f^3-192f\Omega^4+768\Omega^6) \\ & -B^2\Omega^2 a_3(f^3-64f^2\Omega^2+704f\Omega^4-2304\Omega^6) \end{aligned} \right] \cos \Omega t \\
 & -\frac{B^3 f}{6 \times 512\Omega^5(f-8\Omega^2)} \left[ \begin{aligned} & a_2(f^3-192f\Omega^4+768\Omega^6) \\ & -a_4\Omega^2(49f^3-1152f^2\Omega^2+8640f\Omega^4-20736\Omega^6) \end{aligned} \right] \sin \Omega t \\
 & +\frac{B}{64\Omega^4(f-8\Omega^2)} \left[ \begin{aligned} & 8\Omega^2(f-8\Omega^2)^2 + 2B^2Q(f^3-15f^2\Omega^2+80f\Omega^4+64\Omega^6) \\ & +B^2\Omega^2 a_3(3f^3-58f^2\Omega^2+432f\Omega^4-1152\Omega^6) \end{aligned} \right] \cos 3\Omega t \\
 & -\frac{B^3(f-9\Omega^2)}{576\Omega^5(f-8\Omega^2)} \left[ \begin{aligned} & 2a_2(f^3-15f^2\Omega^2-24f\Omega^4+576\Omega^6) \\ & +a_4\Omega^2(25f^3-522f^2\Omega^2+3888f\Omega^4-10368\Omega^6) \end{aligned} \right] \sin 3\Omega t \tag{46} \\
 & +\frac{B^3 f}{512\Omega^4}(f-8\Omega^2) \{ [6Q - a_3(f+6\Omega^2)] \cos 5\Omega t - \Omega [10a_2 - 9a_4(f-6\Omega^2)] \sin 5\Omega t \} \\
 & -\frac{B^3}{4 \times 512\Omega^6}(f-8\Omega^2)^2 [3(Q-5a_3\Omega^2)\cos 7\Omega t - f\Omega(7a_2-27a_4\Omega^2)\sin 7\Omega t] \\
 & +\frac{B^3}{4 \times 512\Omega^6}(f-8\Omega^2)^3 [(Q-9a_3\Omega^2)\cos 9\Omega t - 3\Omega(a_2-9a_4\Omega^2)\sin 9\Omega t],
 \end{aligned}$$

where the amplitude  $B$  is given by

$$B^2 = -\frac{192a_1\Omega^4(f-8\Omega^2)}{2a_2(f^3-15f^2\Omega^2+72f\Omega^4-192\Omega^6)+a_4\Omega^2(25f^3-522f^2\Omega^2+3888f\Omega^4-10368\Omega^6)}. \quad (47)$$

As a result of the removing the secular terms from equation (31), taking into account the case of  $\Omega = \frac{1}{3}\omega$ , the characteristic equation has been evaluated in the following form:

$$h_5\Omega^{10} + h_4\Omega^8 + h_3\Omega^6 + h_2\Omega^4 + h_1\Omega^2 + h_0 = 0. \quad (48)$$

The coefficients that appear in the above dispersion relation are:

$$\begin{aligned} h_5 &= 46656, \\ h_4 &= \frac{216}{a_4} [8a_1a_3 + 8a_2 - 3a_4(27f + 8\omega_0^2)], \\ h_3 &= \frac{3}{a_4} [24a_1(8Q - 9fa_3) - 8a_2(27f + 8\omega_0^2) + 27fa_4(29f + 24\omega_0^2)], \\ h_2 &= -\frac{3f}{2a_4} [2a_1(72Q - 29fa_3) - 6a_2(15f + 8\omega_0^2) + 3fa_4(25f + 58\omega_0^2)], \\ h_1 &= \frac{f^2}{2a_4} [a_1(90Q - 9fa_3) - 6a_2(3f + 5\omega_0^2) + 25fa_4\omega_0^2], \\ h_0 &= \frac{f^3}{a_4} (a_2\omega_0^2 - 3a_1Q). \end{aligned} \quad (49)$$

Stability conditions can be performed as follows:

Five changes of sign in the characteristic equation (48) signify the presence of positive roots. Therefore the requirements of positive roots are

$$h_4, h_2, h_0 < 0, \text{ and } h_3h_1 > 0. \quad (50)$$

The necessary and sufficient conditions for all roots of (48) to be real [28] are

$$h_i^2 - \frac{n-i+1}{n-i} \times \frac{i+1}{i} h_{i-1}h_{i+1} \geq 0; \quad i = 1: 4. \quad (51)$$

Satisfying conditions (50) and conditions (51) together, ensure that the solution (46) has a periodic form.

## 5. Conclusions

In this work, we present the basic theoretical efforts that are known in order to deal with non-trivial solutions of the van der Pol oscillator. We obtain analytic approximation solutions for the generalized cubic van der Pol-Duffing equation. We also construct a set of stability criteria in order to ensure the presence of the periodic solutions. The homotopy frequency method is used to derive an expression for approximate nonlinear frequency for the autonomous case. The derivation has been extended for the non-autonomous case where the forcing van der Pol's equation is considered. A polynomial with a quadratic form in the nonlinear frequency  $\omega^2$  is obtained for the non-forcing van der Pol's equation. In the presence of the forcing,  $f \cos \Omega t$  the nonlinear frequency has formulated as a quadratic form in  $\Omega^2$  at the harmonic resonance case. In the case of the sub-harmonic resonance case, a polynomial of quadratic in  $\omega^2$  has been imposed. In the final case, a quintic polynomial in  $\Omega^2$  has been governed the super-harmonic resonance case. Periodic solutions are generated under an urgent condition on the frequency  $\omega$  to be a real quantity. This requires that all roots of the dispersion relations must be real and positive quantities. Satisfying these requirements imposes some conditions, for the first-time, known as the stability conditions.

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