

INTEGRATION ON HYPERCIRCLES IN \mathbb{R}^n

Grzegorz Biernat¹, Magdalena Ligus², Jarosław Siedlecki¹

¹ Institute of Mathematics, Czestochowa University of Technology, Poland

² Faculty of Mechanical Engineering and Computer Science
Czestochowa University of Technology, Poland

Abstract. This paper presents the formulas parametrizing hypercircles (the intersections of hyperplanes with the sphere in \mathbb{R}^n , $n \geq 3$). A hypothesis concerning the integral on hypercircle C_{n-2} of the $n-2$ - canonical form ω_{n-2} is proposed.

1. Parametrization of hypercircles

A plane circle with the centre at 0 and radius r , has the given parametrization

$$\begin{cases} x = r \cos t \\ y = r \sin t \end{cases} \quad (0 \leq t \leq 2\pi) \quad (1)$$

How about the case of a circle in 3-dimensional space? It is easy to imagine, but how to describe it? Certainly, as an intersection of a plane with a sphere. If we restrict our considerations to circles with the centre at 0, then the system of equation is given as

$$\begin{aligned} Ax + By + Cz &= 0 && (\text{plane}, A^2 + B^2 + C^2 > 0) \\ x^2 + y^2 + z^2 &= r^2 && (\text{sphere}, r > 0) \end{aligned} \quad (2)$$

The parametrizations, mentioned above, are difficult to apply in integration around circle. Thus, parametric description is used. The construction follows.

1° $A = B = 0$. Then, the circle is described by parametrization

$$\begin{cases} x = r \cos t \\ y = r \sin t \\ z = 0 \end{cases} \quad (0 \leq t \leq 2\pi) \quad (3)$$

2° $A^2 + B^2 > 0$. In this case, we construct on the plane $Ax + By + Cz = 0$ a set of orthogonal vectors $[B, -A, 0]$, $[AB, AC, -A^2 - B^2]$ and $[A, B, C]$. We obtain the following orthonormal basis in the space \mathbb{R}^3 :

$$v_1 = \left[\frac{B}{\sqrt{A^2 + B^2}}, \frac{-A}{\sqrt{A^2 + B^2}}, 0 \right] \quad (4)$$

$$v_2 = \left[\frac{AC}{\sqrt{A^2 + B^2} \cdot \sqrt{A^2 + B^2 + C^2}}, \frac{BC}{\sqrt{A^2 + B^2} \cdot \sqrt{A^2 + B^2 + C^2}}, \frac{-A^2 - B^2}{\sqrt{A^2 + B^2} \cdot \sqrt{A^2 + B^2 + C^2}} \right] \quad (5)$$

$$v_3 = \left[\frac{A}{\sqrt{A^2 + B^2 + C^2}}, \frac{B}{\sqrt{A^2 + B^2 + C^2}}, \frac{C}{\sqrt{A^2 + B^2 + C^2}} \right] \quad (6)$$

The parametrized circle in the above coordinate system has a typical description given by formula (3).

We obtain the system of equations

$$\begin{bmatrix} \frac{B}{\sqrt{A^2 + B^2}} & \frac{-A}{\sqrt{A^2 + B^2}} & 0 \\ \frac{AC}{\sqrt{A^2 + B^2} \sqrt{A^2 + B^2 + C^2}} & \frac{BC}{\sqrt{A^2 + B^2} \sqrt{A^2 + B^2 + C^2}} & \frac{-A^2 - B^2}{\sqrt{A^2 + B^2} \sqrt{A^2 + B^2 + C^2}} \\ \frac{A}{\sqrt{A^2 + B^2 + C^2}} & \frac{B}{\sqrt{A^2 + B^2 + C^2}} & \frac{C}{\sqrt{A^2 + B^2 + C^2}} \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} r \cos t \\ r \sin t \\ 0 \end{bmatrix} \quad (7)$$

where the determinant of the coefficient matrix is equal to 1.

The solution of the system looks as follows

$$x = r \left(\frac{B}{\sqrt{A^2 + B^2}} \cos t + \frac{AC}{\sqrt{A^2 + B^2} \sqrt{A^2 + B^2 + C^2}} \sin t \right) \quad (8)$$

$$y = r \left(-\frac{A}{\sqrt{A^2 + B^2}} \cos t + \frac{BC}{\sqrt{A^2 + B^2} \sqrt{A^2 + B^2 + C^2}} \sin t \right) \quad (9)$$

$$z = -r \sqrt{\frac{A^2 + B^2}{A^2 + B^2 + C^2}} \sin t \quad (10)$$

where $0 \leq t \leq 2\pi$.

Thereafter, we consider the case, where hyperplane H_n is defined by

$$A_1x_1 + A_2x_2 + \dots + A_nx_n = 0, \quad A_1^2 + A_2^2 + \dots + A_n^2 > 0, \quad n \geq 3 \quad (11)$$

and sphere S_n intersects \mathbf{R}^n

$$x_1^2 + x_2^2 + \dots + x_n^2 = r^2, \quad r > 0 \quad (12)$$

Let us refer to these as intersections hypercircles C_{n-2} (for $n = 3$ we obtain a circle). Obviously, hypercircles C_{n-2} have the dimension $n - 2$. Next, the following orthogonal versors can be constructed (the first $n - 1$ on hyperplane H_n).

Let us assume that $A_1 \neq 0$.

The *first versor* is defined as

$$v_1 = \left[\frac{A_2}{\sqrt{A_1^2 + A_2^2}}, \frac{-A_1}{\sqrt{A_1^2 + A_2^2}}, 0, \dots, 0 \right] \quad (13)$$

Certainly, v_1 is orthogonal to the vector $[A_1, A_2, \dots, A_n]$ and $v_1 \subset H_n$.

We determine versor v_2 by adopting the following formula

$$v_2 = \left[\frac{A_1A_3}{\sqrt{(A_1^2 + A_2^2)(A_1^2 + A_2^2 + A_3^2)}}, \frac{A_2A_3}{\sqrt{(A_1^2 + A_2^2)(A_1^2 + A_2^2 + A_3^2)}}, \right. \\ \left. \frac{-A_1^2 - A_2^2}{\sqrt{(A_1^2 + A_2^2)(A_1^2 + A_2^2 + A_3^2)}}, 0, \dots, 0 \right] \quad (14)$$

versor v_2 is orthogonal to vectors $[A_1, A_2, \dots, A_n]$, v_1 and $v_2 \subset H_n$.

The *third versor* is defined as follows

$$v_3 = \left[\frac{A_1A_4}{\sqrt{(A_1^2 + A_2^2 + A_3^2)(A_1^2 + A_2^2 + A_3^2 + A_4^2)}}, \frac{A_2A_4}{\sqrt{(A_1^2 + A_2^2 + A_3^2)(A_1^2 + A_2^2 + A_3^2 + A_4^2)}}, \right. \\ \left. \frac{A_3A_4}{\sqrt{(A_1^2 + A_2^2 + A_3^2)(A_1^2 + A_2^2 + A_3^2 + A_4^2)}}, \frac{-A_1^2 - A_2^2 - A_3^2}{\sqrt{(A_1^2 + A_2^2 + A_3^2)(A_1^2 + A_2^2 + A_3^2 + A_4^2)}}, 0, \dots, 0 \right] \quad (15)$$

Versor v_3 is orthogonal to vectors $[A_1, A_2, \dots, A_n]$, v_1 , v_2 and $v_3 \subset H_n$.

Generally, we obtain (applying the vector product [1, 5])

$$v_k = \left[\frac{A_1 A_{k+1}}{\sqrt{(A_1^2 + \dots + A_k^2)(A_1^2 + \dots + A_{k+1}^2)}}, \dots, \frac{A_k A_{k+1}}{\sqrt{(A_1^2 + \dots + A_k^2)(A_1^2 + \dots + A_{k+1}^2)}} \right. \\ \left. , \frac{-A_1^2 - \dots - A_k^2}{\sqrt{(A_1^2 + \dots + A_k^2)(A_1^2 + \dots + A_{k+1}^2)}}, 0, \dots, 0 \right] \quad (16)$$

for $1 \leq k \leq n-1$ (if $k = n-1$, then the last component is not 0).

Evidently versor v_k is orthogonal to the vectors $[A_1, A_2, \dots, A_n]$, v_1, \dots, v_{k-1} and $v_k \subset H_n$.

The last versor

$$v_n = \left[\frac{A_1}{\sqrt{A_1^2 + A_2^2 + \dots + A_n^2}}, \frac{A_2}{\sqrt{A_1^2 + A_2^2 + \dots + A_n^2}}, \dots, \frac{A_n}{\sqrt{A_1^2 + A_2^2 + \dots + A_n^2}} \right] \quad (17)$$

is orthogonal to hyperplane H_n .

Let us define matrix U as follows

$$U := [v_1, v_2, v_3, \dots, v_n]^T \quad (18)$$

Next, we recall sphere parameterization [1, 2, 4]

$$\begin{aligned} x_1 &= r \cos t_1 \cos t_2 \dots \cos t_{n-1} \\ x_2 &= r \sin t_1 \cos t_2 \dots \cos t_{n-1} \\ x_3 &= r \sin t_2 \cos t_3 \dots \cos t_{n-1} \\ &\dots\dots\dots\dots\dots\dots\dots\dots\dots \\ x_{n-1} &= r \sin t_{n-2} \cos t_{n-1} \\ x_n &= r \sin t_{n-1} \end{aligned} \quad (19)$$

where $0 \leq t_1 \leq 2\pi$, $-\frac{\pi}{2} \leq t_j \leq \frac{\pi}{2}$, $2 \leq j \leq n-1$.

We calculate the hypercircle parametrization by solving the following system of equations

$$U \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \dots \\ x_{n-1} \\ x_n \end{bmatrix} = \begin{bmatrix} r \cos t_1 \cos t_2 \dots \cos t_{n-2} \\ r \sin t_1 \cos t_2 \dots \cos t_{n-2} \\ r \sin t_1 \cos t_2 \dots \cos t_{n-2} \\ \dots \\ r \sin t_{n-2} \\ 0 \end{bmatrix} \quad (20)$$

Because matrix U is orthogonal, the solution is given by vector

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \dots \\ x_{n-1} \\ x_n \end{bmatrix} = U^T \cdot \begin{bmatrix} r \cos t_1 \cos t_2 \dots \cos t_{n-2} \\ r \sin t_1 \cos t_2 \dots \cos t_{n-2} \\ r \sin t_1 \cos t_2 \dots \cos t_{n-2} \\ \dots \\ r \sin t_{n-2} \\ 0 \end{bmatrix} \quad (21)$$

2. Integration around hypercircles

We calculate some integrals around circle C_1 in \mathbf{R}^3 and hypercircle C_2 in \mathbf{R}^4 [6]. Using the results from the previous section (three dimensional case of intersection of a sphere with the equation $x^2 + y^2 + z^2 = r^2$ of the plane $Ax + By + Cz = 0$ where $A^2 + B^2 + C^2 > 0$) we can calculate the following integral:

$$\int_{C_1} \frac{Bz - Cy}{x^2 + y^2 + z^2} dx + \frac{Cx - Az}{x^2 + y^2 + z^2} dy + \frac{Ay - Bx}{x^2 + y^2 + z^2} dz \quad (22)$$

The above integral is given by the formula

$$\int_{C_1} \frac{Bz - Cy}{x^2 + y^2 + z^2} dx + \frac{Cx - Az}{x^2 + y^2 + z^2} dy + \frac{Ay - Bx}{x^2 + y^2 + z^2} dz = \int_0^{2\pi} \frac{1}{x^2 + y^2 + z^2} \begin{vmatrix} A & x & \frac{dx}{dt} \\ B & y & \frac{dy}{dt} \\ C & z & \frac{dz}{dt} \end{vmatrix} dt = \int_0^{2\pi} \frac{1}{x^2 + y^2 + z^2} |U^T| \cdot \begin{vmatrix} A' & r \cos t & -r \sin t \\ B' & r \sin t & r \cos t \\ C' & 0 & 0 \end{vmatrix} dt = \quad (23)$$

$$\int_0^{2\pi} \frac{1}{r^2} \cdot C' \cdot r^2 \cdot \begin{vmatrix} \cos t & -\sin t \\ \sin t & \cos t \end{vmatrix} dt = \int_0^{2\pi} C' dt = 2\pi \sqrt{A^2 + B^2 + C^2}$$

where

$$\begin{bmatrix} A' \\ B' \\ C' \end{bmatrix} = U \cdot \begin{bmatrix} A \\ B \\ C \end{bmatrix} \quad (24)$$

Thus, integral (22) is equal to the length of a circle with the radius $\sqrt{A^2 + B^2 + C^2}$ [6]. We can now consider and calculate the following integrate on hypercircle C_2 in \mathbf{R}^4 :

$$\begin{aligned} & \int_{C_2} \frac{\begin{vmatrix} A_4 & A_3 \\ x_4 & x_3 \end{vmatrix}}{(x_1^2 + x_2^2 + x_3^2 + x_4^2)^{\frac{3}{2}}} dx_1 \wedge dx_2 - \frac{\begin{vmatrix} A_4 & A_2 \\ x_4 & x_2 \end{vmatrix}}{(x_1^2 + x_2^2 + x_3^2 + x_4^2)^{\frac{3}{2}}} dx_1 \wedge dx_3 + \\ & \frac{\begin{vmatrix} A_3 & A_2 \\ x_3 & x_2 \end{vmatrix}}{(x_1^2 + x_2^2 + x_3^2 + x_4^2)^{\frac{3}{2}}} dx_1 \wedge dx_4 + \frac{\begin{vmatrix} A_4 & A_1 \\ x_4 & x_1 \end{vmatrix}}{(x_1^2 + x_2^2 + x_3^2 + x_4^2)^{\frac{3}{2}}} dx_2 \wedge dx_3 - \\ & \frac{\begin{vmatrix} A_3 & A_1 \\ x_3 & x_1 \end{vmatrix}}{(x_1^2 + x_2^2 + x_3^2 + x_4^2)^{\frac{3}{2}}} dx_2 \wedge dx_4 - \frac{\begin{vmatrix} A_2 & A_1 \\ x_2 & x_1 \end{vmatrix}}{(x_1^2 + x_2^2 + x_3^2 + x_4^2)^{\frac{3}{2}}} dx_3 \wedge dx_4 = \\ & \int_0^{2\pi} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \frac{1}{(x_1^2 + x_2^2 + x_3^2 + x_4^2)^{\frac{3}{2}}} \cdot \begin{vmatrix} A_1 & x_1 & \frac{\partial x_1}{\partial t_1} & \frac{\partial x_1}{\partial t_2} \\ A_2 & x_2 & \frac{\partial x_2}{\partial t_1} & \frac{\partial x_2}{\partial t_2} \\ A_3 & x_3 & \frac{\partial x_3}{\partial t_1} & \frac{\partial x_3}{\partial t_2} \\ A_4 & x_4 & \frac{\partial x_4}{\partial t_1} & \frac{\partial x_4}{\partial t_2} \end{vmatrix} dt_2 dt_1 = \quad (25) \\ & \int_0^{2\pi} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \frac{1}{(r^2)^{\frac{3}{2}}} |U^T| \cdot \begin{vmatrix} A'_1 & r \cos t_1 \cos t_2 & -r \sin t_1 \cos t_2 & -r \cos t_1 \sin t_2 \\ A'_2 & r \sin t_1 \cos t_2 & r \cos t_1 \cos t_2 & -r \sin t_1 \sin t_2 \\ A'_3 & r \sin t_2 & 0 & r \cos t_2 \\ A'_4 & 0 & 0 & 0 \end{vmatrix} dt_2 dt_1 = \\ & \int_0^{2\pi} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \frac{1}{r^3} \cdot A'_4 \cdot r^3 \cdot \cos t_2 dt_2 dt_1 = A'_4 \int_0^{2\pi} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos t_2 dt_2 dt_1 = A'_4 \int_0^{2\pi} dt_1 \sin t_2 \Big|_{-\frac{\pi}{2}}^{\frac{\pi}{2}} = \\ & 2A'_4 \cdot 2\pi = 4\pi \cdot A'_4 = 4\pi \sqrt{A_1^2 + A_2^2 + A_3^2 + A_4^2} , \end{aligned}$$

where

$$\begin{bmatrix} A'_1 \\ A'_2 \\ A'_3 \\ A'_4 \end{bmatrix} = U \cdot \begin{bmatrix} A_1 \\ A_2 \\ A_3 \\ A_4 \end{bmatrix} \quad (26)$$

We observe that integral (25) is equal to the surface of a sphere with the radius $\sqrt{A_1^2 + A_2^2 + A_3^2 + A_4^2}$ [6]. The above results suggest the following hypothesis.

3. Hypothesis

Integral around hypercircle C_{n-2} of the $n-2$ - canonical form [3]

$$\omega_{n-2} = \frac{(-1)^{n-1}}{(x_1^2 + \dots + x_n^2)^{\frac{n-1}{2}}} \sum_{\substack{1 \leq i_1 < i_2 < \dots < i_{n-2} \leq n \\ j_1, j_2 \neq i_1, i_2, \dots, i_{n-2}}} \text{sgn} (i_1, \dots, i_{n-2}, j_1, j_2) \times \\ \det \begin{bmatrix} A_{j_1} & A_{j_2} \\ x_{j_1} & x_{j_2} \end{bmatrix} dx_{i_1} \wedge dx_{i_2} \wedge \dots \wedge dx_{i_{n-2}} \quad (27)$$

is equal to

$$\int_{C_{n-2}} \omega_{n-2} = \left(\begin{array}{c} \text{surface of} \\ (n-2)\text{-dimensional unit sphere [1]} \end{array} \right) \sqrt{A_1^2 + A_2^2 + \dots + A_n^2} \quad (28)$$

Parametrizations and some integrals around hyperspheres will be presented in the next paper.

References

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