

ONE DIMENSIONAL PHONONIC FDTD ALGORITHM AND TRANSFER MATRIX METHOD IMPLEMENTATION FOR SEVERIN APERIODIC MULTILAYER

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Abstract. In this paper, the power spectrum and phononic properties of the quasi one-dimensional Severin aperiodic multilayer was investigated. Multilayer phononic structures with their phononic band gap properties can be used as filters of mechanical waves. In the paper, the implementation of the Finite Difference Time Domain (FDTD) algorithm with discrete Fourier transform and the Transfer Matrix Method algorithm in the Wolfram Language in Mathematica was made.

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1. Introduction

The structure and geometry of amorphous phononic superlattices determines transmission properties of the analyzed structures - forbidden gaps can be observed [1, 2]. The band gap structure allows for the design of acoustic devices which can be used as acoustic/elastic filters, noise control or acoustic waveguides [3-7]. Some structures where the passband occurs into the band gap can be used for demultiplexing or as selective filters of acoustic wave [8, 9].

1.1. Finite Difference Time Domain algorithm

The Finite Difference Time Domain (FDTD) algorithm can be used for acoustic wave simulation [10] and also for electromagnetic simulation [10-12]. In the case considered, it will take into account pressure waves, and will omit elastic waves. Water was chosen as the background medium. The first order acoustic equation is defined as

$$\frac{1}{\rho_0 \rho_r c^2} \frac{\partial}{\partial t} p(\vec{x}, t) = \nabla \cdot \vec{u} \quad (1)$$

$$\rho_0 \rho_r \frac{d}{dt} \vec{u}(\vec{x}, t) = \nabla p(\vec{x}, t) \quad (2)$$

where:

$$p(\vec{x}, t) - \text{pressure field } \left[\frac{\text{N}}{\text{m}^2} \right] = \left[\frac{\text{kg}}{\text{m} \cdot \text{s}^2} \right],$$

$$\vec{u}(\vec{x}, t) - \text{vector velocity field } \left[\frac{\text{m}}{\text{s}} \right],$$

$$\rho_0 - \text{mass density of water } \left[\frac{\text{kg}}{\text{m}^3} \right],$$

ρ_r - relative to ρ_0 mass density of the medium,

c - velocity of sound.

Gradient is defined by

$$\nabla F = \left(\frac{\partial F}{\partial x_1}, \frac{\partial F}{\partial x_2}, \dots, \frac{\partial F}{\partial x_n} \right) \quad (3)$$

Divergence in Cartesian coordinates is

$$\nabla \cdot F = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \cdot (F_x, F_y, F_z) = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z} \quad (4)$$

It can be defined compressibility $\kappa \left[\frac{\text{m} \cdot \text{s}^2}{\text{kg}} \right]$ as

$$\kappa = \frac{1}{\rho c^2} = \frac{1}{\rho_0 \rho_r c^2}. \quad (5)$$

After simple calculations, the equation (1) can be written as

$$\frac{dp(x, y, z, t)}{dt} = \frac{1}{\kappa(x, y, z)} \left[\frac{du_x(x, y, z, t)}{dx} + \frac{du_y(x, y, z, t)}{dy} + \frac{du_z(x, y, z, t)}{dz} \right] \quad (6)$$

After first-order differencing in space and time, the equation above can be written as

$$\begin{aligned}
 \frac{p^{n+\frac{1}{2}}(i, j, k) - p^{n-\frac{1}{2}}(i, j, k)}{\Delta t} &= \frac{1}{\kappa(x, y, z)} \left[\frac{u_x^n(i+1/2, j, k) - u_x^n(i-1/2, j, k)}{\Delta x} \right] \\
 &+ \frac{1}{\kappa(x, y, z)} \left[\frac{u_y^n(i, j+1/2, k) - u_y^n(i, j-1/2, k)}{\Delta y} \right] \\
 &+ \frac{1}{\kappa(x, y, z)} \left[\frac{u_z^n(i, j, k+1/2) - u_z^n(i, j, k-1/2)}{\Delta z} \right]
 \end{aligned} \tag{7}$$

After subsequent conversions, it was obtained

$$\begin{aligned}
 p^{n+\frac{1}{2}}(i, j, k) &= p^{n-\frac{1}{2}}(i, j, k) \\
 &+ \frac{\rho_0 \rho_r c^2 \Delta t}{\Delta x} \left[u_x^n(i+1/2, j, k) - u_x^n(i-1/2, j, k) \right] \\
 &+ \frac{\rho_0 \rho_r c^2 \Delta t}{\Delta y} \left[u_y^n(i, j+1/2, k) - u_y^n(i, j-1/2, k) \right] \\
 &+ \frac{\rho_0 \rho_r c^2 \Delta t}{\Delta z} \left[u_z^n(i, j, k+1/2) - u_z^n(i, j, k-1/2) \right]
 \end{aligned} \tag{8}$$

Similar calculations of Eq. (2) allowed one to receive

$$\begin{aligned}
 u_x^{n+1}(i+1/2, j, k) &= u_x^n(i+1/2, j, k) \\
 &+ \frac{\Delta t}{\rho_r(i+1/2, j, k) \rho_0 \Delta x} \left[p^{n+1/2}(i+1, j, k) - p^{n+1/2}(i, j, k) \right],
 \end{aligned} \tag{9}$$

$$\begin{aligned}
 u_y^{n+1}(i, j+1/2, k) &= u_y^n(i, j+1/2, k) \\
 &+ \frac{\Delta t}{\rho_r(i, j+1/2, k) \rho_0 \Delta y} \left[p^{n+1/2}(i, j+1, k) - p^{n+1/2}(i, j, k) \right],
 \end{aligned} \tag{10}$$

$$\begin{aligned}
 u_z^{n+1}(i, j, k+1/2) &= u_z^n(i, j, k+1/2) \\
 &+ \frac{\Delta t}{\rho_r(i, j, k+1/2) \rho_0 \Delta z} \left[p^{n+1/2}(i, j, k+1) - p^{n+1/2}(i, j, k) \right].
 \end{aligned} \tag{11}$$

Simplified to a one-dimensional case, it was obtained

$$p^{n+1/2}(k) = p^{n-1/2}(k) + ga(k) \left[u_z^n(k+1/2) - u_z^n(k-1/2) \right] \tag{12}$$

$$u_z^{n+1}(k+1/2) = u_z^{n+1}(k+1/2) + gb(k+1/2) \left[p^{n+1/2}(k+1) + p^{n+1/2}(k) \right] \quad (13)$$

where

$$ga(k) = \frac{\rho_0 \rho_r c^2 \Delta t}{\Delta z} \quad (14)$$

$$gb(k+1/2) = \frac{\Delta t}{\rho_r(k+1/2) \rho_0 \Delta z} \quad (15)$$

The Courant equation determined the Δt and Δz parameters

$$\Delta t \leq \frac{\Delta z}{c_{\max}} \quad (16)$$

c_{\max} is the fastest velocity of sound in the simulation.

1.2. Discrete Fourier Transform

All implementation used in the paper was made in the Wolfram Language in Mathematica. The definition of discrete Fourier transform f_s of a list u_r of length n is described by the equation

$$v_s = \frac{1}{\sqrt{n}} \sum_{r=1}^n u_r e^{\frac{2\pi i(r-1)(s-1)}{n}} \quad (17)$$

The power spectrum is defined by

$$F(f_s) = Abs(f_s) \quad (18)$$

and the results are normalized in frequency domain.

1.3. Transfer Matrix Method algorithm

The Transfer Matrix Method (TMM) algorithm can be used to analyze 1D phononic crystal transmission properties for acoustic/elastic waves. The equation (19) describes the pressure of the acoustic wave which is propagating in a multilayer medium from left to right.

$$\frac{1}{v_i^2} \frac{\partial^2 p}{\partial t^2} - \nabla^2 p = 0 \quad (19)$$

Where v_i is the acoustic wave phase velocity and the corresponding layer is described by subscript i . The solution of one-dimensional plane wave takes the form

$$p_i = P_i(x) e^{-i\omega t} = (A_i e^{ik_i x} + B_i e^{-ik_i x}) e^{-i\omega t} \quad (20)$$

The first term on the right side of equation (20) is the transmitted wave and the second is reflected one. The f is frequency in the wave number described as $k_i = \frac{2\pi f}{v_i}$.

The transmission coefficient is defined as

$$T = \left| \frac{1}{\Gamma_{1,1}} \right|^2 \quad (21)$$

where Γ is the characteristic matrix for the multilayer structure described by

$$\Gamma = \Xi_{in,1} \Psi_1 \Xi_{1,2} \Psi_2 \Xi_{2,3} \Psi_3 \Xi_{3,4} \Psi_4 \cdots \Xi_{n-2,n-1} \Psi_{n-1} \Xi_{n-1,n} \Psi_n \Xi_{n,out} \quad (22)$$

$\Xi_{i,j}$ is the matrix which describes the interfaces between the layers and is defined as

$$\Xi_{i,j} = \frac{1}{2} \begin{bmatrix} \frac{\rho_i v_i + \rho_j v_j}{\rho_i v_i} & \frac{\rho_i v_i - \rho_j v_j}{\rho_i v_i} \\ \frac{\rho_i v_i + \rho_j v_j}{\rho_i v_i} & \frac{\rho_i v_i - \rho_j v_j}{\rho_i v_i} \end{bmatrix} \quad (23)$$

In the equation above, ρ_i is mass density of layer i . Propagation in layer i is defined by the matrix

$$\Psi_i = \begin{bmatrix} e^{i\varphi_{v,d_i,v_i}} & 0 \\ 0 & e^{-i\varphi_{v,d_i,v_i}} \end{bmatrix} \quad (24)$$

The φ function takes the form

$$\varphi_{f,d_i,v_i} = \frac{2\pi f d_i}{v_i} \quad (25)$$

where d_i is the thickness of layer i .

1.4. Severin superlattice

Using the recursive rule of substitution, the aperiodic Severin structure X_L^S [13] can be obtained

$$\begin{cases} A \rightarrow BB \\ B \rightarrow AB \end{cases} \quad (26)$$

$X_0^S = B$ is the initial condition. The generations where L is respectively equal to 3, 4 and 5 in the Severin superlattice are described by the formula (26) and listed in Table 1. Initial structural values are defined as:

$$\begin{aligned} X_0^S &= B \\ X_1^S &= AB \\ X_2^S &= BBAB \end{aligned} \quad (27)$$

Table 1

Arrangement of the layers structure for L generations of the Severin superlattices

L	X_L^S
3	ABABBBAB
4	BBABBBABABBBAB
5	ABABBBABABABBBABBBABBBABABABBBAB

2. Implementation

2.1. TMM initialization

The listing below shows the variable initialization. The lx describes the superlattice structure made from A and B materials types with initial values of properties vl , rol and dl . Where vl is phase velocity of the medium, rol is mass density and dl is thickness of the layer.

```
nr = 1;
lx = {{A, B, A, B}};
f0 = v0;
v1 = Join[{v_in}, lx[nr]] /. {A -> v_A, B -> v_B, F -> v_F}, {v_out};
ro1 = Join[{rho_in}, lx[nr]] /. {A -> rho_A, B -> rho_B, F -> rho_F}, {rho_out};
d1 = Join[{d_in}, lx[nr]] /. {A -> d_A, B -> d_B, F -> d_F}, {d_out};
```

The listing below corresponds to equations (21), (22), (23), (24) and (25). The T function returns the transmission coefficient for a given structure and frequency.

$$\phi_{i, \nu, \nu_-, d} := \frac{2 \pi \nu d_{[i]}}{V_{[i]}}$$

$$\Psi_{i, \nu, \nu_-, d} := \begin{pmatrix} e^{i \phi_{i, \nu, \nu_-, d}} & 0 \\ 0 & e^{-i \phi_{i, \nu, \nu_-, d}} \end{pmatrix}$$

$$\Xi_{i, \rho, \nu_-} := \frac{1}{2} \begin{pmatrix} \frac{\rho_{[i+1]} V_{[i+1]} + \rho_{[i]} V_{[i]}}{\rho_{[i+1]} V_{[i+1]}} & \frac{\rho_{[i+1]} V_{[i+1]} - \rho_{[i]} V_{[i]}}{\rho_{[i+1]} V_{[i+1]}} \\ \frac{\rho_{[i+1]} V_{[i+1]} - \rho_{[i]} V_{[i]}}{\rho_{[i+1]} V_{[i+1]}} & \frac{\rho_{[i+1]} V_{[i+1]} + \rho_{[i]} V_{[i]}}{\rho_{[i+1]} V_{[i+1]}} \end{pmatrix}$$

$$\Gamma_{d, \nu_-, \rho, \nu_-} := \Xi_{1, \rho, \nu_-} \cdot \text{Table}[\Psi_{i, \nu, \nu_-, d} \cdot \Xi_{i, \rho, \nu_-}, \{i, 2, \text{Length}[\rho] - 1\}]$$

$$T_{d, \nu_-, \rho, \nu_-} := \text{Abs} \left[\frac{1}{\Gamma_{d, \nu_-, \rho, \nu_-}[1, 1]} \right]^2$$

2.2. Implementation of FDTD

The *sev** variables describes aperiodic Severin superlattice structures which are given in Table 1. In *param* are the properties of surrounding medium and properties of used materials. The *cmax* parameter is the maximum velocity in the simulation which is needed to calculate *dt* from the Courant condition. The *freqIn* is a frequency and *npml* is number of PML boundary conditions. The *grA* and *grB* are thickness of layers *A* and *B* respectively. After that, there are the *roStruct* and *cStruct* functions which initialize the material constants of the studied structure. The first two sub-lists in the parameter *param* define the symbol of the input *in* and output *out* material. The structure of the remaining sub-lists is constructed in the following way: the first element is the symbol of a given material, the second is the material density [kg/m³], the third is phase velocity [m/s], and the last is the material name.

```

sev12 = {B, B, A, B};
sev13 = {A, B, A, B, B, B, A, B};
sev14 = {B, B, A, B, B, B, A, B, A, B, A, B, B, A, B};
sev15 = {A, B, B, A, B, A, A, B, B, A, A, B, A, B, B, A, B, A, A, B, A, B, B,
        A, A, B, B, A, B, A, A, B};
param = {{in, A, 0, 0}, {out, A, 0, 0}, {A, 1000, 1500, "woda"},
        {B, 7800, 5900, "stal"}};
cmax = 10 000;
dz = .1;
dt = dz / cmax;
freqIn = 200;
npml = npml = 50;
kc = ile / 2; t0 = 150.; spread = 50; t = 0; nsteps = 1;
grA = 20;
grB = 20;
grIn = 2 npml + 60;
    
```

```

grubSieci[siec_] := Length[Position[siec, A]] grA + Length[Position[siec, B]] grB +
  grIn
wybranoSiec = sev15;
ile = grubSieci[wyranoSiec];
p = u = Table[0, {ile}];
pml = {p + 1, p + 1, u + 1, p + 1};
roStruct[siec_] := Flatten[Join[
  Table[
    param[[Position[Transpose[param][[1]],
      param[[Position[Transpose[param][[1]], in][[1, 1]], 2]][[1, 1]], 2]],
    {npml + 30}],
  siec /. {A → Table[param[[Position[Transpose[param][[1]], A][[1, 1]], 2]], {grA}},
    B → Table[param[[Position[Transpose[param][[1]], B][[1, 1]], 2]], {grB}}},
  Table[
    param[[Position[Transpose[param][[1]],
      param[[Position[Transpose[param][[1]], out][[1, 1]], 2]][[1, 1]], 2]],
    {npml + 30}]
  ]]
cStruct[siec_] := Flatten[Join[
  Table[
    param[[Position[Transpose[param][[1]],
      param[[Position[Transpose[param][[1]], in][[1, 1]], 2]][[1, 1]], 2]],
    {npml + 30}],
  siec /. {A → Table[param[[Position[Transpose[param][[1]], A][[1, 1]], 3]], {grA}},
    B → Table[param[[Position[Transpose[param][[1]], B][[1, 1]], 3]], {grB}}},
  Table[
    param[[Position[Transpose[param][[1]],
      param[[Position[Transpose[param][[1]], out][[1, 1]], 2]][[1, 1]], 2]],
    {npml + 30}]
  ]]
ro = roStruct[wyranoSiec];
c = cStruct[wyranoSiec];

```

In the *For* loop below, the PML boundary conditions are initialized.

```

For[i = 1, i ≤ npml, i++,
  xxn = (npml - i) / npml;
  xn = .33 * xxn^3;
  pml[[1, ile - i - 1]] = pml[[1, i]] = 1 / (1 + xn);
  pml[[2, ile - i - 1]] = pml[[2, i]] = (1 - xn) / (1 + xn);
  xxn = (npml - i - 0.5) / npml;
  xn = .33 * xxn^3;
  pml[[3, ile - i - 2]] = pml[[3, i]] = 1 / (1 + xn);
  pml[[4, ile - i - 2]] = pml[[4, i]] = (1 - xn) / (1 + xn);
]
pt = {};

```

Main loop alternately calculates equations (12) and (13). As can be seen, *pulse* is soft sinusoidal source with *freqIn* frequency.


```

Animate[
  t++;
  For[k = 2, k ≤ ile, k++,
    p[[k]] = pml[[2, k]] p[[k]] + pml[[1, k]] ((dt ro[[k]] c[[k]] ^ 2) / dz)
      (u[[k - 1]] - u[[k]]);];
  pulse = Sin[5 × 2 Pi freqIn dt t];
  p[[npml + 15]] += pulse;
  For[k = 1, k < ile, k++,
    u[[k]] = pml[[4, k]] u[[k]] + pml[[3, k]] (dt / (ro[[k]] dz)) (p[[k]] - p[[k + 1]]);];
  AppendTo[pt, p[[ile - npml - 15]]];
  If[t == 10 000, Abort[]];
  ListPlot[p, Joined → True, PlotRange → {-6, 6}, PlotLabel → ToString[t]
    , {a, 0, 100}]

```

According to Equations (17) and (18), the Discrete Fourier Transform and the power spectrum are designated by

```

lf1 = Abs[Fourier[pt]];
maxlf1 = Max[lf1];
lf2 = Table[x / (dt Length[lf1]), {x, 1, Length[lf1]}];
lf3 = Transpose[{lf2, lf1 / maxlf1}];
rl = ListLinePlot[lf3, PlotRange → {{0, 3200}, All}, Frame → True,
  FrameLabel → {"f", "F(v)"}]

```

3. Research

In this paper, the properties of aperiodic Severin superlattices were analyzed. Input and output medium was material *A* which was water with a mass density of 1000 kg/m^3 and a phase velocity of 1500 m/s ; *B* material was steel with parameters respectively 7800 kg/m^3 and 5900 m/s . Thickness of the single layer *A* or *B* was equal 0.1 m . Figure 1 shows TMM results for Severin aperiodic superlattice with generation number L equal to 3, 4 or 5. By analyzing the results, it can be seen that as the complexity of the structure increases and the number of transmission bands increases as well. An interesting result can be observed for frequency f_0 on Figure 1d, where $L = 3$ there is almost no acoustic wave transmission, then for $L = 4$ there is a transmission peak equal to half of the maximal value, and for $L = 5$ the peak doubles its intensity.

After passing through the multilayer structure, after multiple reflections within the composite, the superposition of acoustic waves occurs in the output. The output signal can be analyzed using the Discrete Fourier Transforms. Figure 2 shows the power spectrum after t steps of FDTD simulation for each considered L generation of the Severin multilayer. Source frequency was set to 734.88 Hz . As shown in Figure 2, the output signal at the frequency domain shows the presence of peaks. For an 8-layered structure of $L = 3$ generation (Fig. 2a) there are observed in frequency domain in 3.69 kHz and 3.81 kHz . Below 3 kHz for L equal to 3 and 4 there are no peaks observed. After doubling the complexity of the Severin structure ($L = 4$, Fig. 2b) maximum function values occurs at 3.69 , 3.76 and 3.8 kHz .

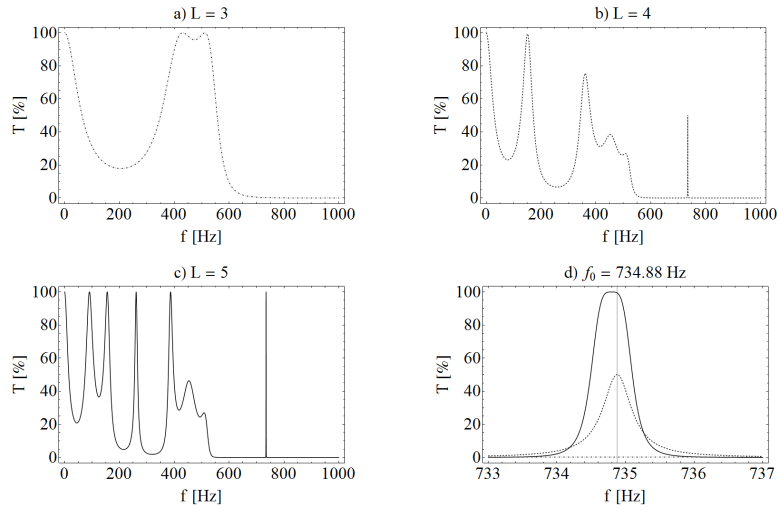


Fig. 1. Transmission maps of Severin superlattices calculated by the TMM algorithm for L generations respectively a) $L = 3$, b) $L = 4$, c) $L = 5$, d) transmission values for f_0 frequency are collected in Table 2

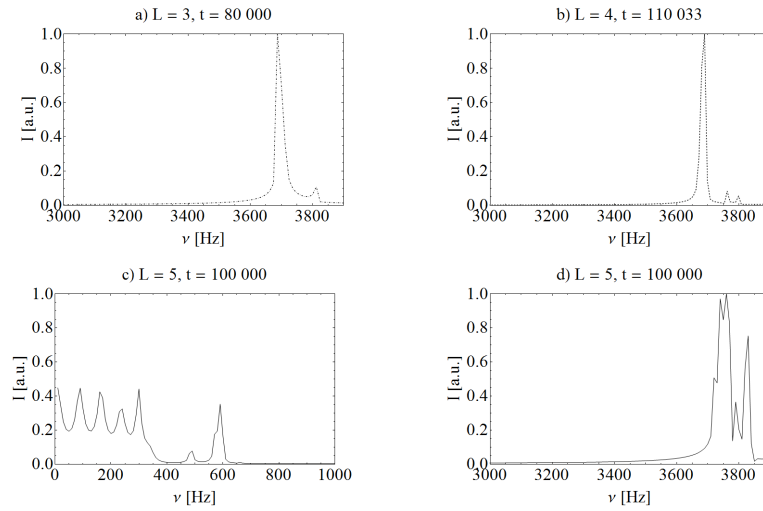


Fig. 2. Power spectrum of Severin superlattices calculated by FDTD with DFT algorithm for source frequency $f_0 = 734.88$ Hz; a) $L = 3$, b) $L = 4$, c) $L = 5$, frequency range up to 1 kHz, d) $L = 5$, frequency range from 3 to 3.9 kHz

Table 2

Transmission values for generation number L in $f_0 = 734.88$ Hz

L	3	4	5
T	0.24%	50.1%	99.35%

A much more interesting situation occurs for $L = 5$ (Fig. 2c) where there are components with frequencies below 650 Hz with maxima of 90, 160, 240, 300, 490,

590 Hz. In the range of 3.6÷3.9 kHz, maximum frequencies occur at 3.72, 3.74, 3.76, 3.79 and 3.83 kHz.

4. Conclusions

The transmission properties of the aperiodic filters structure obtained using the TMM algorithm are very important for many types of acoustic devices such as selective filters, wave guides, noise control or demultiplexing. The output signal properties can be studied by FDTD with DFT.

In the paper, transmission properties of an aperiodic Severin multilayer structure was analyzed. The TMM algorithm shows the passband of the investigated filter. The most interesting was the appearance of a narrow band at $f_0 = 734.88$ Hz which can be used as selective filter. The structure of the output signal was analyzed and for $L = 5$ generation of the filter appeared signal below 650 Hz.

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