

IMAGE DENOISING USING NEW WAVELET THRESHOLDING FUNCTION

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Abstract. In this paper, we propose a new image denoising method based on wavelet thresholding. In this method, we introduce a new nonlinear thresholding function characterized by a shape parameter and basic properties. These characteristics make the new method able to achieve a compromise between both traditional thresholding techniques such as Hard and Soft thresholding. The experimental results show that our proposed method provides better performance compared to many classical thresholding methods in terms of the visual quality of the denoised image.

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1. Introduction

Recovering an image that is corrupted by a noise during its acquisition or transmission is an open issue in the field of image processing and computer vision problems. Many researchers have been interested in noise reduction methods. These methods aim to recover the image in a way to be as close as possible to the original image. A vast number of papers about classical techniques in the spatial and transform domain has been published in literature [1]. Recently, the Multi-Diagonal Matrix Filter (MDMF) [2] and Lambda Multi-Diagonal Matrix Filter (Lambda-MDMF) [3] are proposed methods for image denoising at level of the spatial domain, which have given best performance compared to the Mean and Median filter [1]. At present, the most commonly used method for noise removal is the Discrete Wavelet Transform (DWT) [4, 5], which has given main contributions to image compression and denoising [6, 7]. In this approach, the thresholding of wavelet coefficients is a basic step in the denoising algorithm, where via a selected threshold value, only a small number of wavelet coefficients contain the

necessary information of the image. Donoho and Johnstone [8] have proposed the hard and the soft thresholding techniques, that are the first and most widely used in image denoising with the Universal Threshold value (UT) [8]. In addition, the hard thresholding function is discontinuous and the soft thresholding function is continuous with a discontinuous derivative.

However, the thresholding techniques still suffer from the selection of the convenient threshold value. Then, the optimization methods as Stein's Unbiased Risk Estimate (SURE) [9] requires the second derivative of the thresholding function for obtaining an optimal threshold value. Further, Tang et al. [10] have considered that the differentiability of the thresholding function make the reconstructed signal more smoother.

For this purpose, in this paper, we propose a new class of a smooth nonlinear thresholding function based on the Gauss error function in its mathematical expression. This new thresholding function has high order derivatives into subintervals and characterized by a shape parameter, that can make it flexibly adjusted when we change the parameter value. Moreover, the simulation results have proved that the denoising using this new thresholding function has provided better performance compared to many other thresholding methods in terms of the visual quality of the denoised image.

This work is organized as follows: The next section recalls the principle of the wavelet denoising with an additive Gaussian noise. Section 3 introduces the classical thresholding methods and main shrinkage rule. Section 4 presents the new denoising method that is characterized by a new nonlinear thresholding function and describes the procedure of the proposed denoising method algorithm. Section 5 compares the simulation results of our proposed method with other thresholding methods.

Finally, we close this work by a conclusion and main references.

2. Noise reduction based on wavelet denoising

Let us consider an original image f of size $N \times M$ pixels, that will be recovered. Assume that f is corrupted by an independent and an identically (i, i, d) zero mean white Gaussian noise n with standard deviation σ . The observed noisy image g will be given by this relation:

$$g(i, j) = f(i, j) + n(i, j), \quad i = 1, \dots, N, \quad j = 1, \dots, M \quad (1)$$

The goal of threshold denoising is to remove the noise from g by estimating \tilde{f} , which minimizes the mean square error (MSE) risk defined as:

$$MSE = \frac{1}{N \times M} \sum_{j=1}^M \sum_{i=1}^N (\tilde{f}(i, j) - f(i, j))^2 \quad (2)$$

Then, \tilde{f} maximizes the Peak Signal to Noise Ratio (PSNR) in dB, that is written by:

$$PSNR = 10 \log_{10} \left(\frac{255^2}{MSE} \right) \quad (3)$$

In the wavelet domain, the Discrete Wavelet Transform (DWT) decomposes the noisy image g into the following orthonormal bases at level J ($J \geq 1$):

$$\left\{ \Psi_{J-1,(k,l)}^{(i)}, i=1,2,3, (k,l) \in \mathbf{Z}^2 \right\} \cup \left\{ \phi_{J-1,(k,l)}, (k,l) \in \mathbf{Z}^2 \right\} \quad (4)$$

where

$$\begin{aligned} \Psi_{J-1,(k,l)}^{(1)}(x,y) &= 2^{J-1} \phi(2^{J-1}x - k) \psi(2^{J-1}y - l) \\ \Psi_{J-1,(k,l)}^{(2)}(x,y) &= 2^{J-1} \psi(2^{J-1}x - k) \phi(2^{J-1}y - l) \\ \Psi_{J-1,(k,l)}^{(3)}(x,y) &= 2^{J-1} \psi(2^{J-1}x - k) \psi(2^{J-1}y - l) \\ \phi_{J-1,(k,l)}(x,y) &= 2^{J-1} \phi(2^{J-1}x - k) \phi(2^{J-1}y - l) \end{aligned}$$

and ϕ, ψ are respectively, the scaling and wavelet functions [5].

Then, the decomposition into $\left\{ \phi_{J-1,(k,l)}, (k,l) \in \mathbf{Z}^2 \right\}$, $\left\{ \Psi_{J-1,(k,l)}^{(1)}, (k,l) \in \mathbf{Z}^2 \right\}$, $\left\{ \Psi_{J-1,(k,l)}^{(2)}, (k,l) \in \mathbf{Z}^2 \right\}$ and $\left\{ \Psi_{J-1,(k,l)}^{(3)}, (k,l) \in \mathbf{Z}^2 \right\}$ produces four subbands, are respectively LL, LH, HL and HH (see Fig. 1). The HH, HL and LH are called detail subbands and LL is called an approximation subband.

The wavelet thresholding denoising method processes each coefficient from the detail subbands with a thresholding function to obtain \bar{g} . Then, the denoised estimation image \tilde{f} of the original image f is the inverse discrete wavelet transform (IDWT) of \bar{g} , i.e, $\tilde{f} = IDWT(\bar{g})$.

LL	HL
LH	HH

Fig. 1. Decomposition at level $J = 1$

3. Wavelet denoising using thresholding function

In the wavelet denoising, the way to perform denoising on images is by thresholding. The thresholding is a simple technique applied to wavelet coefficients using a thresholding function η . The function η should be characterized by a threshold value λ ($\lambda > 0$) and two basic properties such as: Elimination of the small wavelet coefficients and reduction of the effect of large coefficients.

Donoho and Johnstone [8] have introduced two primary thresholding methods, which are Hard and Soft thresholding.

The Hard thresholding kills the wavelet coefficients, whose absolute values are lower than the threshold and keeps the other coefficients. The Hard thresholding function is expressed as follows:

$$\eta_H(x, \lambda) = \begin{cases} x & \text{if } |x| > \lambda \\ 0 & \text{if } |x| \leq \lambda \end{cases} \quad (5)$$

The Soft thresholding kills the coefficients, whose absolute values are lower than the threshold and shrinks the nonzero coefficients towards zero. The soft thresholding function is defined as:

$$\eta_S(x, \lambda) = \begin{cases} x - \lambda & \text{if } x > \lambda \\ x + \lambda & \text{if } x < -\lambda \\ 0 & \text{if } |x| \leq \lambda \end{cases} \quad (6)$$

Note that the Hard thresholding function is discontinuous at $|x| = \lambda$. Due to this discontinuity, this function yields artifacts in the denoised image. Whereas, the Soft thresholding function is continuous, so that the pseudo Gibbs phenomena can be avoided. But, when we reduce the coefficients by the threshold value, then in some cases the reconstructed image will be motivated by some deviations. Then, to overcome these drawbacks, Gao [11] considered the nonnegative Garrote thresholding function, which is continuous and shrinks or kills the coefficients. On the other hand, this thresholding function offers samples of advantages. The Garrote thresholding function is given by:

$$\eta_G(x, \lambda) = \begin{cases} x - \frac{\lambda^2}{x} & \text{if } |x| > \lambda \\ 0 & \text{if } |x| \leq \lambda \end{cases} \quad (7)$$

and performs better than the two precedent thresholding techniques in terms of the visual quality of the denoised image.

In another side, the choice of a suitable threshold value is subject to shrinkage rules. Donoho and Johnstone [8] have proposed the Visu Shrink rule, where the threshold value is the Universal Threshold (UT) and defined as follows:

$$\lambda = \sigma \sqrt{2 \log(N \times M)} \quad (8)$$

where σ^2 is the noise variance and $N \times M$ represents the size of the image. Moreover, the noise level σ can be estimated according to this formula [8]:

$$\hat{\sigma} = \frac{\text{Median}(|y_{i,j}|)}{0.6745}, \quad y_{i,j} \in \text{subband}(HH_1) \quad (9)$$

This method yields the best performance when the number of the pixels reaches infinity. Further, it can only deal with an additive Gaussian noise.

4. Presentation of the new denoising method

4.1. Proposed nonlinear thresholding function

The continuity in the Soft thresholding function is better property, but its first derivative is discontinuous and constant. So, in order to overcome the shortcomings of the Hard and the Soft thresholding functions, we propose an alternative thresholding function that verifies a compromise between both traditional thresholding functions. This new thresholding function is based on the Gauss Error Function in its mathematical expression and characterized by a shape parameter α ($\alpha > 0$). Its expression is given by the following formula:

$$\eta_{New,\alpha}(x, \lambda) = \begin{cases} x - \lambda + \frac{2\lambda}{\sqrt{\pi}} \int_0^{\alpha \frac{x-\lambda}{\lambda}} e^{-t^2} dt & \text{if } x > \lambda \\ 0 & \text{if } |x| \leq \lambda \\ x + \lambda - \frac{2\lambda}{\sqrt{\pi}} \int_0^{\alpha \frac{x+\lambda}{\lambda}} e^{-t^2} dt & \text{if } x < -\lambda \end{cases} \quad (10)$$

This thresholding function is constructed for to be continuous and graphically located between the Hard and the Soft thresholding function.

From (10), we can conclude that: when $|x| = \lambda$, $\eta_{New,\alpha}(x, \lambda) = 0$ and when $|x| \rightarrow \lambda$, $\eta_{New,\alpha}(x, \lambda) \rightarrow 0$. Then, the new thresholding function is continuous at the threshold point λ . If $|x| \rightarrow +\infty$, $\eta_{New,\alpha}(x, \lambda) \rightarrow x$, which can be seen that with increasing x , $\eta_{New,\alpha}(x, \lambda)$ becomes gradually close to x , then $\eta_{New,\alpha}$ has the same

asymptotic convergence rate as the Hard and Soft thresholding function. Furthermore, the shape parameter α can be adjusted freely such as, when $\alpha \rightarrow 0$, $\eta_{New,\alpha}(x, \lambda) \rightarrow \eta_S(x, \lambda)$ and when $\alpha \rightarrow +\infty$, $\eta_{New,\alpha}(x, \lambda) \rightarrow \eta_H(x, \lambda)$ (see Fig. 2).

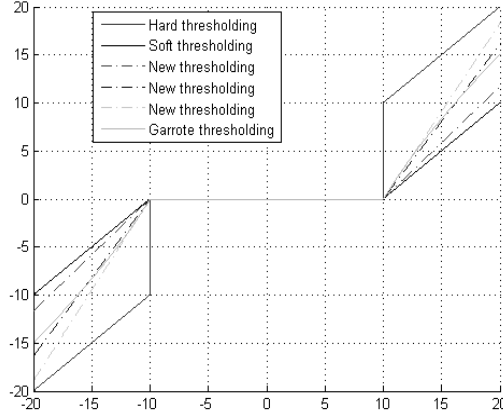


Fig. 2. Graph of Hard, Soft, Garrote and Proposed thresholding with ($\alpha = 0.05$, $\alpha = 0.2$, $\alpha = 0.3$) respectively at $\lambda = 10$

Moreover, this new thresholding function has the following properties:

Theorem 1. The New thresholding function $\eta_{New,\alpha}$ is graphically located between the Hard and the Soft thresholding function.

Proof: We put for all x ,

$$f(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$$

Then, f is increasing function in the domain of $]-\infty, +\infty[$ and has the following properties:

$$\begin{aligned} \forall x \geq 0, \quad 0 &\leq f(x) \leq 1 \\ \forall x \leq 0, \quad -1 &\leq f(x) \leq 0 \\ \forall x > 0, \quad f(-x) &= -f(x) \end{aligned}$$

Thus for $x > \lambda$, we have $0 \leq f\left(\alpha \left(\frac{x-\lambda}{\lambda}\right)\right) \leq 1$

then, $x - \lambda \leq \eta_{New,\alpha}(x, \lambda) \leq x$.

For $x < -\lambda$, then $\alpha\left(\frac{x+\lambda}{\lambda}\right) < 0$ and

$$-\frac{2}{\sqrt{\pi}} \int_{\alpha\left(\frac{x+\lambda}{\lambda}\right)}^0 e^{-t^2} dt = f\left(\alpha\left(\frac{x+\lambda}{\lambda}\right)\right) = -f\left(-\alpha\left(\frac{x+\lambda}{\lambda}\right)\right)$$

This yields,

$$-1 \leq -\frac{2}{\sqrt{\pi}} \int_{\alpha\left(\frac{x+\lambda}{\lambda}\right)}^0 e^{-t^2} dt \leq 0$$

Then,

$$x \leq \eta_{New,\alpha}(x, \lambda) \leq x + \lambda$$

For $|x| \leq \lambda$, the functions $\eta_{New,\alpha}$, η_H and η_S are equal to zero.

Theorem 2. The New thresholding function $\eta_{New,\alpha}$ is continuous in the domain of $]-\infty, +\infty[$.

Proof: Since $\eta_{New,\alpha}$ is continuous at $|x| = \lambda$, then $\eta_{New,\alpha}$ is continuous everywhere.

Theorem 3. The New thresholding function $\eta_{New,\alpha}$ is monotonous in the domain of $]-\infty, +\infty[$.

Proof: For $x < -\lambda$, we have

$$\eta'_{New,\alpha}(x, \lambda) = 1 + \frac{2\alpha}{\sqrt{\pi}} e^{-\alpha^2\left(\frac{x+\lambda}{\lambda}\right)^2} > 0 \quad (11)$$

In another side, if $x > \lambda$, then

$$\eta'_{New,\alpha}(x, \lambda) = 1 + \frac{2\alpha}{\sqrt{\pi}} e^{-\alpha^2\left(\frac{x-\lambda}{\lambda}\right)^2} > 0 \quad (12)$$

Since $\eta_{New,\alpha}$ is continuous everywhere, then $\eta_{New,\alpha}$ is monotonous in the domain of $]-\infty, +\infty[$.

Theorem 4. The New thresholding function $\eta_{New,\alpha}$ has high order derivatives into subintervals $]-\infty, -\lambda[$ and $]\lambda, +\infty[$.

Proof: From (11) and (12), we conclude that $\eta_{New,\alpha}$ has high order derivatives into subintervals $]-\infty, -\lambda[$ and $]\lambda, +\infty[$.

Remark 1. Since $\eta_{New,\alpha}$ has high order derivatives into subintervals, then the denoised image will be smooth.

Remark 2. In the literature, there are various optimization methods for determining an optimal shape parameter, whose Mean Square Error is as little as possible.

4.2. Proposed denoising method algorithm

In this subsection, we illustrate the basic steps concerning the procedure of the proposed denoising method algorithm with its flowchart (see Fig. 3).

Step 1. Load the noisy image.

Step 2. Apply the Discrete Wavelet Transform at level J for the noisy image, then we get (LL, LH, HL, HH).

Step 3. Estimate the noise level σ using (9).

Step 4. Select the shrinkage rule applied to the proposed thresholding function.

Step 5. Take the Inverse Discrete Wavelet Transform to the thresholded components.

Step 6. Get the denoised image.

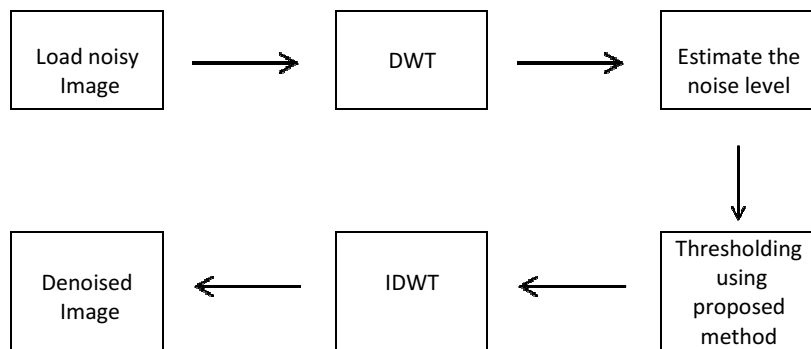


Fig. 3. Flowchart corresponding to the proposed method algorithm

5. Experimental results and discussion

In order to verify the effectiveness of our proposed denoising method, we compare it with the classical thresholding methods such as Hard, Soft and Garrote thresholding using the Visu Shrink rule. These thresholding methods are applied to various noisy test images of 512×512 pixels, that are corrupted by a Gaussian noise with different noise levels σ (see Fig. 4). The wavelet that is used in all methods is the Haar wavelet in the decomposition level $J = 1$, where the optimal shape parameter is determined by a stochastic approximation method (Robbins-Monro algorithm) [12]. So, the simulation results using Matlab are presented in Table 1.

Table 1

Comparison of PSNR (dB) results between the classical and proposed denoising methods

Images	Noise level	Hard	Soft	Garrote	Proposed method	Shape parameter
Barbara	10	28.0440	27.7677	27.7094	28.1019	0.009
	15	24.6469	24.6132	24.5666	25.2104	0.01
	20	22.3580	22.4018	22.5437	22.6088	0.05
	25	20.0717	19.6226	20.1902	20.4312	0.1
	30	18.1999	18.1438	18.3651	18.5197	1
Boat	10	25.7620	27.7896	27.3350	27.8906	0.009
	15	24.6985	24.2036	24.7721	25.0008	0.15
	20	21.8492	22.1981	21.4785	22.2295	0.15
	25	19.9245	20.0176	20.1240	20.4384	1
	30	18.0349	18.6323	18.5476	18.7409	0.05
Cameraman	10	27.8897	28.1068	28.0274	28.1492	0.09
	15	22.9283	22.4868	22.8450	23.1930	0.9
	20	19.2072	18.9017	18.8856	19.2539	0.09
	25	16.1831	16.0629	15.7873	16.2988	0.25
	30	13.5814	13.2885	13.4052	13.6726	1

This Table presents the PSNR values corresponding to each image at different noise levels. The PSNR is a denoising criterion used to evaluate the quality of the denoised image, where the higher PSNR produces better denoising quality. Apparently, the experimental results show that at each noise level the PSNR that corresponds to our proposed method is the highest compared to all other methods for each image. Furthermore, the outperformance of the Garrote method for each

image compared to the Hard and the Soft method appears at the high noise levels due to the selection of the threshold value. Whereas, our proposed method avoids this problem due to the existence of the shape parameter. Thus, our proposed denoising method outperforms all other denoising methods in terms of the visual quality of the denoised image (see Fig. 5).



Fig. 4. Original and corrupted images for Barbara with Gaussian noise level ($\sigma = 20$)

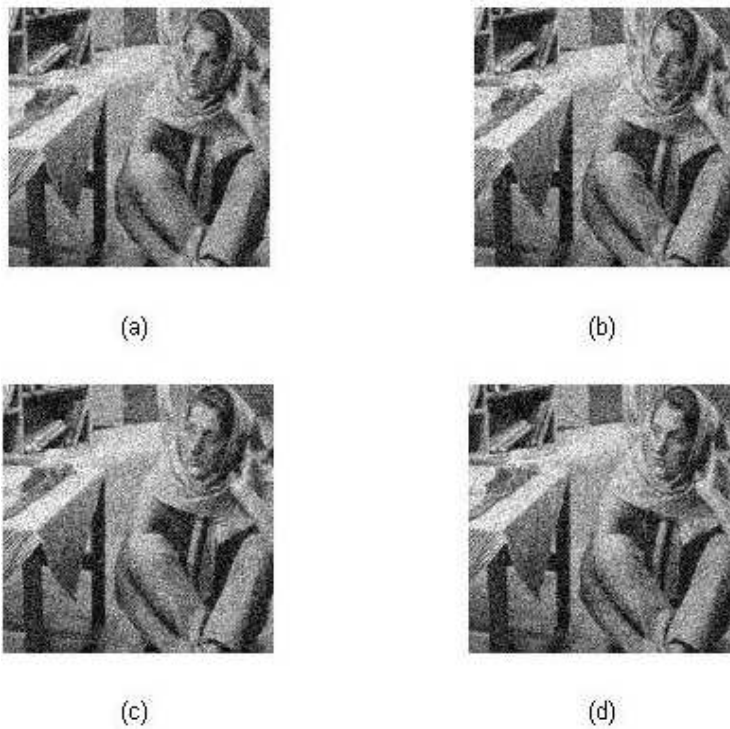


Fig. 5. Denoised images, (a), (b), (c), (d) using Hard, Soft, Garrote and Proposed method respectively at Gaussian noise level ($\sigma = 20$)

6. Conclusions

In this paper, we have developed a new image denoising method based on wavelet thresholding. In this new denoising method, the thresholding function is characterized by many mathematical properties, where our proposed method can overcome the shortcomings of the classical thresholding methods. The experimental results with many test images have shown the outperformance of our denoising method compared to Hard, Soft and Garrote thresholding methods in terms of the Peak Signal to Noise Ratio (PSNR), where our proposed method has given the highest PSNR.

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